

**Zero-speed monitor**

- Application up to SIL 3 according to EN 61508, EN 62061 or PL e / Category 4 according to EN ISO 13849-1
- Manual or automatic reset
- Eight safe inputs and four safe semiconductor outputs
- 2 kHz cutoff frequency
- Adjustable standstill frequency
  - 0.1 Hz...9.9 Hz (0.1 Hz steps) and 0.5 Hz ...99 Hz (1 Hz steps)
- Sensors:
  - Proximity switches with PNP-output (plus switching)
  - Incremental encoder with HTL-output

**Device versions**

SNS 4074K-A	0.1–9.9 Hz	R1.188.3620.0	SNS 4084K-A	0.1–9.9 Hz	R1.188.3660.0
SNS 4074K-C	0.1–9.9 Hz	R1.188.3630.0	SNS 4084K-C	0.1–9.9 Hz	R1.188.3670.0
SNS 4074K-A	0.5–99 Hz	R1.188.3640.0	SNS 4084K-A	0.5–99 Hz	R1.188.3480.0
SNS 4074K-C	0.5–99 Hz	R1.188.3650.0	SNS 4084K-C	0.5–99 Hz	R1.188.3490.0

...-A: with screw terminals, pluggable; ...-C: with spring-loaded terminals, pluggable

**Further Documentation**

For the planning, commissioning and operation of the device, please observe the information in the documentation "Manual SNS 4084K/4074K Standstill Monitor" (Doc. No.: BA000506).

 **SAFETY REGULATIONS**

- The installation, commissioning, modification and retrofitting must only be performed by a qualified electrician.
- Disconnect the device / the system from the power supply before starting work. In the case of installation and system errors, mains voltage can be present on the control circuit in the case of non-galvanically isolated devices.
- Observe the electrotechnical and professional trade association safety regulations for the installation of the equipment.
- Opening the case or other manipulation voids any warranty.

 **ATTENTION**

- In the case of improper use or any use other than for the intended purpose, the device must no longer be used and any warranty claim is void. Invalidating causes can be:
  - strong mechanical loading of the device such as, e.g. in the case of falling or voltages, currents, temperatures, humidity outside the specification.
  - Always check all safety functions in accordance with the applicable regulations during initial commissioning of your machine / system and observe the specified inspection cycles for safety devices.
- Take the following safety precautions before starting installation / assembly or dismantling:
  1. Disconnect the device / the system from the power supply before starting work.
  2. Secure the machine / system against being switched on again.
  3. Confirm that no voltage is present.
  4. Ground the phases and short to ground briefly.
  5. Cover and shield neighbouring live parts.
- Limited contact protection!
  - Protection class according to EN 60529.
  - Case / terminals: IP 40 / IP 20.
  - Finger-proof according to EN 50274.

**Proper Use**

The units must only be used as components of safety devices on machines intended to protect persons, material and machines.

Only use the unit in accordance with its intended purpose. Also, pay particular attention to the information in the technical data.

 **The frequencies present at the inputs 11, 12, 13 and 14 must not exceed 2 kHz (cutoff frequency).**

**NOTE**

- The SIL according to EN 61508 / EN 62061 or PL / Category according to EN ISO 13849-1 depending on the external wiring, the choice of control devices and their location on the machine.
- In applications with a low demand of the safety function, a proof-test once a year has to be implemented (The supply voltage of the device has to be switched off and on again and the safety function of the device has to be activated to verify the safety function).
- The device must be protected with a fuse 4 A Operating Class gG or a circuit breaker 4 A Tripping Characteristics B or C.

**Installation** (see also "Assembly")

**NOTE**

- The devices must be installed in a switch cabinet with a protection class of at least IP 54.
- The installation is made on a mounting rail according to EN 50022-35.
- The mounting rail must be connected to protective earth (PE).
- The external power supply must comply with the regulations for low voltages with safe separation (SELV, PELV according to IEC 60536) and EN 50178 (Electrical equipment for use in power installations).
- External loads must be equipped with a suitable protection circuit for the load (e.g. RC elements, varistors, suppressors) in order to reduce electromagnetic interference and to increase the service life of the output switching elements.

**Functional Description**

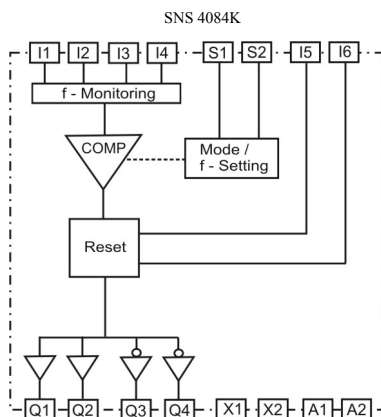
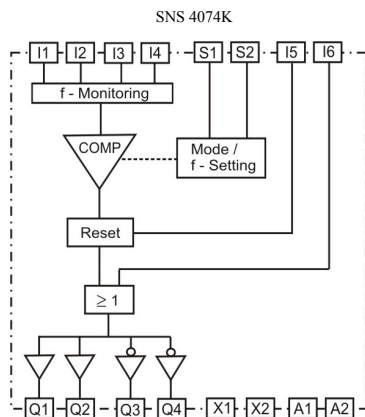
In the SNS 4084K/4074K there are four operating mode groups A, B, C, D available for safe speed monitoring tasks (see manual):

- Zero-speed monitoring (A, B)
- Diverse zero-speed monitoring (C, D) with PLC-signal

**Connections and indicators** (see also the section "Terminal Diagram")

Terminal	Function	LED	Meaning, if LED lights
A1	Operating voltage connection $U_B$	PWR	$U_B$ is present
A2	Operating voltage connection Ground		
X1, X2	Semiconductor signal outputs for indicating and evaluating operating and error statuses		
S1	Input for function selection (operating mode)	S1	High signal is present
S2	Input for function selection (operating mode)	S2	High signal is present
I1 – I4	Inputs for sensor transmitter or Input for function selection (operating mode)	I1 – I4	High signal is present
I5	Input for RESET function	I5	High signal is present
I6	Input for enable/start delay	I6	High signal is present
Q1 / Q2	Outputs (semiconductors), safety related	Q1 / Q2	High signal is present
Q3 / Q4	Inverted outputs (semiconductors), safety related	Q3 / Q4	High signal is present
		ERR	Error (see manual BA000506)

**Settings of the standstill monitor (diagram)**



**Information on the outputs**

The outputs Q1/Q2 can be used up to SIL 3.  
The outputs Q3/Q4 can be used for controlling magnetically operated interlocks up to SIL 1.

X1, X2 are not safe semiconductor outputs.  
X1 signals error states.  
X2 signals the logic state of A and the RESET request by I5.

**Setting of the speed to be monitored**

The standstill frequency is set using the two rotary switches "x" and "y".

Device Variants	Rotary switch	Freq. [Hz]
0.1–9.9 Hz	00 / 01– 99	0.1 / 0.1–9.9
0.5–99 Hz	00 / 01– 99	0,5 / 01–99

**"ENTER" button: Activation of the function block and control circuit functions**

- Set the required operating mode, speed (at the rotary switches) and the control circuit function (using external wiring at S1, S2, I5).
- Then apply the operating voltage with the ENTER button pressed; the ERR indicator flashes (max. 3 s).
- Release the ENTER button while the ERR indicator is flashing (an error is detected if the ENTER button is pressed for longer than 3 s).

The selected operating mode, speed and RESET function are then saved and active.

**RESET / BYPASS function I5/I6 (SNS 4074K)**

The automatic(high)/manual (low) Reset function is defined during the activation of the POU, see ENTER button.

automatic RESET: A High signal at I5 (open) transmits the comparator signal to the outputs.

manual RESET: A High pulse at I5 transmits the enable of the comparator to the outputs.

The transfer of the Reset signals can be influenced using the Bypass function (ODER) at the input I6 of the SNS 4074K. If the input I6 is wired (HIGH), the outputs Q1 and Q2 are permanently HIGH and Q3 and Q4 permanently LOW. The generation of the bypass signal has to fulfill the same safety requirements as the operating mode and the designated safety function.

**RESET / Start-up bridging I5/I6 (SNS 4084K)**

The automatic(high)/manual (low) Reset function is defined during the activation of the POU, see ENTER button.

automatic RESET: A High signal at I5 (open) transmits the comparator signal to the outputs. This transfer can be disabled with I6 (I6 = LOW)

**manual RESET:** A High pulse at I5 transmits the enable of the comparator to the outputs. A High pulse at I6 revokes this enable.

#### Behaviour of the device in the case of an error

The detection of random or systematic system errors in the system or its control results in deactivation. In doing so, all safety-oriented output circuits are switched off and the ERR LED of the module lights or flashes. Error codes are also output via the signal output X1 and the LEDs of the inputs.

Three error categories are distinguished:

- ERR lights: system error, all outputs are deactivated.
- ERR flashes: serious error, all outputs are deactivated.
- ERR off: no errors or minor process errors

Detailed information can be found in the manual.

The deactivation can be revoked if necessary by the user by elimination of an error (e.g. in the control) and by switching off the operating voltage and then switching it on again.

#### Setting the operating mode

Operating mode	Sensor	Input Assignment					
		S1	S2	I1	I2	I3	I4
A-1 A-2	– Incremental encoder with HTL output	low	low	Sensor 1	Sensor 2	Sensor 1 inverted	Sensor 2 inverted
B-1	– Incremental encoder with HTL output – Sensor with PNP output	low	high	Sensor 1	Sensor 1 inverted	low	low
B-2 <sup>1)</sup>	– Sensor with PNP output			Sensor 1	Sensor 2	low	high
B-3	– Incremental encoder with HTL output – Sensor with PNP output			Sensor 1	low	high	low
C-1	– Incremental encoder with HTL output – Sensor with PNP output	high	low	Sensor 1	PLC signal	Sensor 1 inverted	low
C-1	– Incremental encoder with HTL output – Sensor with PNP output			Sensor 1	static HIGH signal	Sensor 1 inverted	high
D-1	– Incremental encoder with HTL output – Sensor with PNP output	high	high	Sensor 1	PLC signal	low	low
D-1	– Incremental encoder with HTL output – Sensor with PNP output			Sensor 1	static HIGH signal	low	high

<sup>1)</sup> In operating mode B-2, the specified safety level can only be adhered to if the sensor lines are individually sheathed and laid so that they are protected.

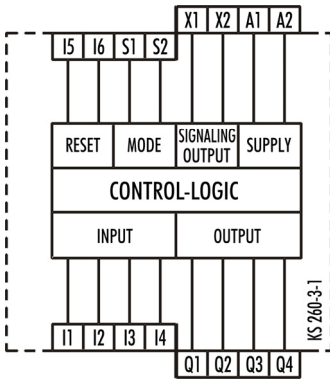
#### Technical Data

		min	typical	max
<b>Power circuit (A1, A2)</b>				
Operating voltage $U_b$ , DC		19,2 V DC	<b>24 V DC</b>	30 V DC
Rated voltage $U_N$		–	<b>24 V DC</b>	–
Residual ripple $U_{ss}$		–	–	3.0 V
Rated power DC		–	2.5 W	3.0 W
Peak current $I_p$		–	–	25 A
Ready time $t_{on}$ (after applying $U_b$ )		5sec. + $1/f_{ST}$		
Fuse Class gG or circuit breaker		4 A (gG)		
<b>Input circuit (I2, I3, I4, I5, I6, S1, S2)</b>				
Input voltage	$U_b$ (HIGH)	13.0 V	–	30 V
	$U_b$ (LOW)	-0.5 V	–	5.0 V
Input current	$I_b$ (HIGH)	2.4 mA	<b>3.0 mA</b>	3.8 mA
	$I_b$ (LOW)	-2.5 mA	–	2.1 mA
Input capacitance, $C_{IN}$		<b>10 nF</b>		
Input resistance $R_{IN}$		<b>7200 <math>\Omega</math></b>		
Duty cycle $t_\xi$		52 ms	–	70 ms
Break time $t_A$		52 ms	–	70 ms
Interruption time of $U_b$ (test pulses)		–	–	4.0 ms
<b>Input circuit (I1, I2, I3, I4)</b>				
Input voltage	$U_b$ (High)	13.0 V	–	30 V
	$U_b$ (LOW)	-0.5 V	–	5 V
Input current	$I_b$ (HIGH)	2.4 mA	–	3.8 mA
	$I_b$ (LOW)	-2.5 mA	–	2.1 mA
Input capacitance, $C_{IN}$		<b>10 nF</b>		
Input resistance $R_{IN}$		<b>7200 <math>\Omega</math></b>		
Cutoff frequency		2 kHz		
Frequency change		21 kHz/s		
Measurement accuracy of the frequency measurement		1% (<1Hz)	6 % (<50Hz)	12 % ( $\leq$ 99Hz)
Pulse duration LOW level (for $f < 100$ Hz)		> 600 $\mu$ s		
Pulse duration High level (for $f < 100$ Hz)		> 600 $\mu$ s		

LOW level (for 100 Hz <math>f < 2 \text{ kHz}</math>)	> 200 $\mu\text{s}$		
High level (for 100 Hz <math>f < 2 \text{ kHz}</math>)	> 200 $\mu\text{s}$		
Output circuit (X1, X2)			
Output voltage	18,4 V	–	30.0 V
Output current	–	–	150 mA
Load capacitance $C_L$	–	–	1000 nF
Line resistance $R_L$ , effective during discharge of $C_L$			100 $\Omega$
Line length (single, $\varnothing 1.5 \text{ mm}^2$ )	–	–	100 m
Short-circuit behaviour	strictly short-circuit protected		
Output circuit (Q1, Q2, Q3, Q4)			
Output voltage	18,4 V	–	30 V
Output current $I_{QnV}$ , $T_U \leq 45^\circ\text{C}$ (resistive / inductive)	–	1.6	2.0 A / 1,0 A
Output current $I_{QnV}$ , $T_U \leq 55^\circ\text{C}$			1,6 A
Sum current $\Sigma I_{QnV}$ , $T_U \leq 45^\circ\text{C}$	–	–	4.0 A
Sum current $\Sigma I_{QnV}$ , $T_U \leq 55^\circ\text{C}$			3.2 A
Test pulse width $t_{PI,HL}$		400 $\mu\text{s}$	650 $\mu\text{s}$
Test pulse period duration $T_{PI,HL}$		192 ms	
Load capacitance $C_L$			500 nF
Inductive cutoff energy E ( $E = 0.5 \cdot L \cdot I^2$ )			370 mJ
Line length (single, $\varnothing 1.5 \text{ mm}^2$ )			100 m
Short-circuit behaviour	strictly short-circuit protected		
Response time ( $t_{AN}$ ) for overspeed for standstill frequency ( $f_{st}$ ) 0.1 HZ - 99 HZ for duty cycle 1:1 (3:2) plus the internal processing time			
	1 / $f_{st}$		1,8 (1,6) / $f_{st}$
	8 ms		12 ms
Error detection time			
Short circuit to GND, $U_B$			
– Incremental encoder HTL	52 ms		116 ms
– Sensors with PNP output (duty cycle 3:2, Mode B-2)	52 ms		3/f
Short circuit to $U_B$ (internal input)			576 ms
Short circuit to $U_B$ (output)			576 ms
Error in the power supply			576 ms

General Data		
Electrical isolation	Power circuit - input circuit	no
	Power circuit - output circuit	no
	Input circuit - output circuit	no
Weight	0.16 kg	
Climatic conditions		
Climatic conditions according to	EN 61131-2	
Ambient operating temperature $T_B$	-25°C to +55°C	
Storage temperature	-25°C to +70°C	
Relative humidity	10% to 95%, no moisture condensation	
Air pressure in operation	860 hPa to 1060 hPa	
Mechanical strength		
Vibration according to	EN 60068-2-xx (see manual for further information)	
Electrical safety		
Protection class according to EN 60529 case/terminals	IP 40 / IP 20	
Finger-proof	EN 50274	
Air gap/Creepage paths	EN 60664-1	
EMC according to	EN 61000-4-xx (see manual for further information)	
Surge voltage category	III	
Degree of soiling	2 inside, 3 outside	
Terminals and connection data	Screw clamp terminals	Spring-loaded terminals
Single-core or finely stranded	1 $\times$ 0.14–2.5 mm <sup>2</sup> / 2 $\times$ 0.14–0.75 mm <sup>2</sup>	2 $\times$ 0.2–1.5 mm <sup>2</sup>
Finely stranded with wire-end ferrule according to DIN 46228	1 $\times$ 0.25–2.5 mm <sup>2</sup> / 2 $\times$ 0.25–0.5 mm <sup>2</sup>	2 $\times$ 0.25–1.5 mm <sup>2</sup> (trapezoid crimping)
AWG	26–14	24–16
Maximum tightening torque	0,5–0,6 Nm (5–7 lbf-in)	–
Stripping length	max. 8 mm	

### Terminal diagram

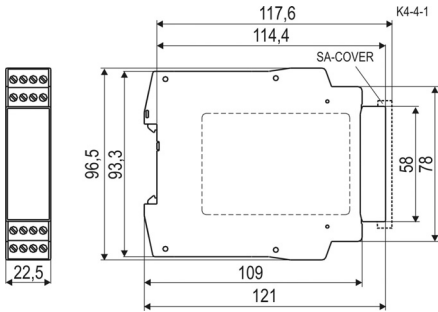


### Assembly, Disassembly

Assembly	
1 ↓	1 Attach device to DIN rail.
2 ↻	2 Press the device carefully onto the DIN rail (in direction of arrow) until it locks into place.
Disassembly	
3 ↓	3 Push device down (in direction of arrow)
4 ↻	4 Release device and remove it from the DIN rail (see arrow)

### Dimension Diagram

SNS 4084K-A DC 24V



SNS 4084K-C DC 24V

