

	Main Featu	res			
	Reference Product code Product line		: NACF\ : 13535 : CFW1 <sup>;</sup>		
Basic data <sup>P</sup> ower supply nput minimum-maximum vol Number of phases nput	tage	: 200-2 : :	40 V		
Output		: 3			
Supply voltage range		200-2	40 V	200	-240 V
Overload regime		Normal (ND)	Heavy (HD)	Normal (ND)	Heavy (HD)
Rated current		10A	8		
Overload current at 60 s		11A	12A		
Overload current at 3 s		15A	16.0		
Maximum applical					
Voltage/Freque			Power (HP /		
		Normal Overload (	ND)	Heavy Ove	
220V / 50H		3 / 2,2		2/1	
220V / 60H		3 / 2,2		2/1	
230V / 50H		3 / 2,2		3/2	
230V / 60H	Z	3 / 2,2		2/*	l,5
RFI internal filter [3] External filter Link Inductor Memory card JSB port Line frequency Line frequency range (minim Phase unbalance Transient voltage and overvor Rated current of single-phase Overload (ND) Overload (HD) Rated current of three-phase Overload (HD) Power factor Displacement factor Rated efficiency Maximum connections (power DC power supply Standard switching frequence Overload HD Selectable switching frequent Real-time clock COPY Function Dissipated power:	oltage e input input er up cycles - on/off) per h	<ul> <li>Not a</li> <li>Yes</li> <li>Incluc</li> <li>Stanc</li> <li>50/60</li> <li>48-62</li> <li>Less</li> <li>Cates</li> <li>Cates</li> <li>10A</li> <li>8 A</li> <li>0,94</li> <li>0,98</li> <li>≥ 979</li> <li>nour</li> <li>60</li> <li>5 kHz</li> <li>5 kHz</li> <li>5 kHz</li> <li>1,25;</li> <li>Yes, i</li> </ul>	: Hz or equal to 3% of ir jory III	nput rated line voltage	9
Mounting type	0	verload		Overload (*	·)
Surface	ND	HD 170 W/		ND	HD Not applicable
Surface Flange	170 W 30 W	170 W 30 W		pplicable pplicable	Not applicable Not applicable
Source available to the Dutput voltage Maximum capacity Control/performance da	user	: 24 Vo : 500 n	nA		
Power supply Control method		: V/f, V	hed-mode power s VW, Vector and PN with 'Slot 2' access	1 motor	
Encoder interface		. Only	WIT SIDEZ ACCESS	0.13	

Control/performance da	ata		
Control output frequency		: 0 to 300 Hz	
Frequency resolution V/F Control		: Equivalent to 1 rpm	
- Speed resolution		: 1% of rated speed	
- Speed range		: 1:20	
VVW Control		. 10/ of rotad around	
<ul> <li>Speed resolution</li> <li>Speed range</li> </ul>		: 1% of rated speed : 1:30	
Sensorless vector control		. 1.00	
- Speed resolution		: 0,5% of rated speed	
- Speed range		: 1:100	
- Speed resolution		: 0,05% of rated speed	
- Speed range		: Up to 0 rpm	
Analog inputs			
Quantity (standard)		:2	
Levels		: 0-10V, 0/4-20mA and -10-+10V	
Impedance - Impedance for voltage inpu	ıt	: 400 kΩ	
- Impedance for current input		: 500 Ω	
Function		: Programmable	
Maximum allowed voltage		: ±30 Vcc	
Digital inputs			
Digital inputs - Quantity (star Activation	noard)	: 6 : Active low and high	
Maximum low level		: 3 V	
Minimum high level		: 18 V	
Input current		: 11 mA	
Maximum input current Function		: 13,5 mA : Programmable	
Maximum allowed voltage		: 30 Vcc	
Analog outputs			
Analogic outputs - Quantity	(standard)	:2	
Levels		: 0 to 10V, 0 to 20mA and 4 to 20mA	
RL for voltage output RL for current output		: 10 kΩ : 500 Ω	
Function		: Programmable	
Digital outputs		-	
Digital outputs - Quantity (sta	andard)	: 3 NO/NC relays	
Maximum voltage		: 240 Vca	
Maximum current Function		: 1 A : Programmable	
Communication		. rogrammabie	
	ory: RS485-01; RS485-05; CAN/RS485-0 prv <sup>.</sup> MODBUSTCP-05)	1; RS232-01 or RS232-05)	
- Profibus DP (with accessor	ry: PROFDP-05)		
- Profibus DPV1 (with acces			
<ul> <li>Profinet (with accessory: P</li> <li>CANopen (with accessory)</li> </ul>	ROFINETIO-05) CAN/RS485-01 or CAN-01)		
	: DEVICENET-05; CAN/RS485-01 or CAI	N-01)	
- EtherNet/IP (with accessor	y: ETHERNET/IP-05 or ETHERNETIP-2F		
- EtherCAT (with accessory:			
· · · · · · · · · · · · · · · · · · ·	S485-01 or CAN/RS485-01)		
<ul> <li>Protections available</li> <li>Output overcurrent/short ci</li> </ul>	ircuit		
- Power supply phase loss			
- Under/Overvoltage in powe	er		
- Overtemperature			
- Motor overload			
- IGBT's modules overload			
<ul> <li>IGBT's modules overload</li> <li>Fault/External alarm</li> </ul>			
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> </ul>			
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> <li>CPU or memory failure</li> </ul>	4 - i i4		
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> <li>CPU or memory failure</li> <li>Output phase-ground short</li> </ul>			
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> <li>CPU or memory failure</li> <li>Output phase-ground short</li> <li>Operation interface (HN)</li> </ul>		· Included in the product	
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> <li>CPU or memory failure</li> <li>Output phase-ground short</li> <li>Operation interface (HN Avaliability</li> </ul>		: Included in the product : Local	
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> <li>CPU or memory failure</li> <li>Output phase-ground short</li> <li>Operation interface (HN)</li> </ul>		: Included in the product : Local : 9	
<ul> <li>Fault/External alarm</li> <li>Breaking resistor overload</li> <li>CPU or memory failure</li> <li>Output phase-ground short</li> <li>Operation interface (HN Avaliability Installation</li> <li>Number of HMI buttons</li> <li>Display</li> </ul>		: Local : 9 : Graphic LCD	
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variable Speed Drives				
Operation interface (HMI)				
Standard HMI degree of protection		: IP56		
HMI battery type		: CR2032		
HMI battery life expectancy		: 10 years		
Remote HMI type		: Detachable of the inv	vortor	
51				
Remote HMI frame		: Accessory		
Remote HMI degree of protection		: IP56		
Ambient conditions				
Enclosure		: IP55		
Degree of pollution		: 2		
Temperature				
- Minimum		: -10 °C / 14 °F		
- Nominal [4]				
Current reduction factor [5]				
Relative humidity (non-condensing)				
- Minimum		: 5%		
- Maximum		: 90%		
Altitude		. 90 /8		
- Rated conditions		· 1000 m (2281 ft)		
		: 1000 m (3281 ft)		
- Maximum altitude allowed for operation		: 4000 m (13123 ft)		
Current Reduction factor[6]	( ))	10/ 6		
- Current derating factor (for altitudes above ra		: 1% for each 100 m a		
<ul> <li>Voltage derating factor (for altitudes above 2</li> </ul>	2000 m / 6562 ft)	: 1,1% for each 100 m	above	
Sustainability policies				
RoHS		: Yes		
Conformal Coating				
-		-		
Dimensions				
Size		: A		
Height		:		
Width		:		
Depth		:		
Weight		:		
Mechanical installation				
		· Surface or flange		
Mounting position		: Surface or flange		
Fixing screw		: M5 : 5 N m / 2 60 lb ft		
Tightening torque		: 5 N.m / 3.69 lb.ft		
Allows side-by-side assembly		: Yes, without top cap		
Minimum spacing around the inverter				
- Тор		: 25 mm / 0.98 in		
- Bottom		: 25 mm / 0.98 in		
- Front	Front			
- Side		: 30 mm / 1.18 in		
Electrical connections				
Cable gauges and tightening torque:				
	Recommended cable		Recommended tightening torque	
	gauge to	75 °C (167 °F)		
Power				
Braking	1.5 mr	m² (16 AWG)		
Grounding	1,0 11			
Control	0.5 to 1.5 m	$m^{2}(20 \text{ to } 14 \text{ A})MC)$	0.5 N.m / 0.37 lb.ft	
Sontion	0,5 to 1,5 mm <sup>2</sup> (20 to 14 AWG)		0,5 11.117 0.57 15.11	
Additional especifications				
Maximum breaking current		: 7,1 A		
Minimum resistance for the brake resistor		: 56 Ω		
Recommended aR fuse		: FNH00-20K-A		
Recommended aR fuse		: Not applicable	•	
Recommended circuit breaker		: ACW100H-FMU20-	3	
Recommended circuit breaker		: Not applicable		
Standarda				
Standards				
Safety		C - Power conversion equi		
			cluding clearances and creepage distanc	
		ical equipment.		
			its electrical, thermal and energy.	
	for electri - EN 618	rical equipment.	its electrical, thermal and energy.	

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EN 50170	Floatronia	a autin mant fr	or waa in nawar	instalations
- EN 301/0-	- Electronic e	equipment id	or use in power	Instalations

- EN 60204-1 - Safety of machinery. Electrical equipment of machines. Part 1: General requirements. Note: To have a machine in accordance with this standard, the machine manufacturer is responsible for installing an emergency stop device and supply disconnecting device. - EN 60146 (IEC 146) - Semiconductor converters.

- EN 61800-2 - Adjustable speed electrical power drive systems - Part 2: General requirements - Rating especifications for low voltage adjustable frequency AC power drive systems.

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Electromagnetic compatibility	EN 61800-3 - Adjustable speed electrical power drive systems - Part 3: EMC
Election agriculo compatibility	product standard including specific test methods.
	- EN 55011 - Limits and methods of measurement of radio disturbance
	characteristics of industrial, scientific and medical (ISM) radio-frequency equipment.
	<ul> <li>CISPR 11 - Industrial, scientific and medical (ISM) radio-frequency equipme</li> <li>Eletromagnetic disturbance characteristics - Limits and methods of measurement.</li> </ul>
	<ul> <li>EN 61000-4-2 - Eletromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 2: Eletrostatic discharge immunity test.</li> <li>EN 61000-4-3 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 3: Radiated, radio-frequency,</li> </ul>
	electromagnetic field immunity test.
	- EN 61000-4-4 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 4: Electrical fast transient/burst immunity test.
	- EN 61000-4-5 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 5: Surge immunity test.
	<ul> <li>EN 61000-4-6 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 6: Immunity to conducted disturbances.</li> </ul>
	induced by radio-frequency fields.
Mechanical construction	<ul> <li>EN 60529 - Degrees of protection provided by enclosures (IP code).</li> <li>UL 50 - Enclosures for electrical equipment.</li> </ul>
	- EN 60529 e UL 50

#### Notes

1) Orientative motor power, valid for WEG Motors standard of IV poles. The correct sizing must be done according to the nominal current of the motor used, which must be less than or equal to the rated output current of the inverter;

2) Braking resistor is not included;

3) With category for emission level conducted;

4) Without derating and with minimum spaces;

5) For temperatures above the nominal and maximum temperature (with derating of current and minimum spaces);

6) For altitude over of specified;

7) All images are merely illustrative;

8) For more information, see the users manual of the CFW-11 (size A).