SSC-T800_{series}



New type with radial cross ray method

- Small objects and flat tape-like objects detected
- Convenient simplified wiring requiring no clock (synchronization) line
- Compact and flat (14.5 mm)
- Water resistance to IP 67

Type

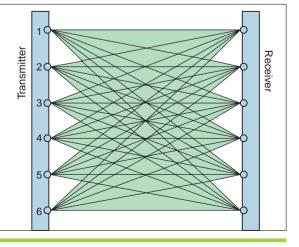
Detection method	Detecting distance	Light axis interval	No. of light axes	Detecting width	Set model No.	Detecting object
	100-500mm	5.55mm	10	- 50mm -	SSC-T801	Opaque object of ϕ 6mm min.
	0.4-1.2m	5.5511111			SSC-T802	Opaque object of ϕ 8mm min.
	0.5-2m	- 12.5mm	5		SSC-T804	Opaque object of ϕ 15mm min.
	100-500mm				SSC-T805	Opaque object of ϕ 12.5mm min.
Through-		16.6mm	10	150mm	SSC-T850	Opaque object of ϕ 17mm min.
beam type	150-800mm	11mm	10		SSC-T810	Opaque object of ϕ 11mm min.
		20mm	6	100mm	SSC-T815	Opaque object of ϕ 20mm min.
	0.5-2.5m	11mm	10	100111111	SSC-T830	Opaque object of ϕ 13mm min.
		20mm	6		SSC-T835	Opaque object of ϕ 22mm min.

Radial Cross Ray Method

The transmitter emits light beams in a scanning manner and receiver accepts light beams of all axes at all times.

When Beam 1 is emitted, all of the receiving elements of the receiver receive the light. The sensor is activated when light beam of any of the light axes is blocked.

The figure on the right shows a model with six light axes. The number of light axes depends on the model.



Rating/Performance/Specification

		Set model No.	SSC-T801 (PN)	SSC-T802(PN)	SSC-T804(PN)	SSC-T805 (PN)	SSC-T850 (PN)	SSC-T810(PN)	SSC-T815(PN)	SSC-T830 (PN)	SSC-T835(PN)	
	Model	Transmitter model No.	SSC-TL801	SSC-TL802	SSC-TL804	SSC-TL805	SSC-TL850	SSC-TL810	SSC-TL815	SSC-TL830	SSC-TL835	
		Receiver model No.	SSC-TR801 (PN)	SSC-TR802(PN)	SSC-TR804 (PN)	SSC-TR805 (PN)	SSC-TR850(PN)	SSC-TR810(PN)	SSC-TR815(PN)	SSC-TR830(PN)	SSC-TR835(PN)	
	Detection method				透過形							
Rating/performance	Detecting distance		100-500mm	0.4-1.2m	0.5-2m	100-500mm	150-800mm		0.5-2.5m		2.5m	
	Detection object		Opaque object of	Opaque object of	Opaque object of	Opaque object of	Opaque object of	Opaque object of	Opaque object of	Opaque object of	Opaque object of	
			φ 6mm min.	∮8 mm min.	φ 15 mm min.	φ 12.5 mm min.	φ 17 mm min.	φ 11 mm min.	φ 20 mm min.	φ 13 mm min.	φ 22 mm min.	
ma	No. of light axes		1	10 5		1	0	6	10	6		
rfor	Detecting width		50mm			150mm			0mm			
/be	Light axis interval 5.		5.55	imm	12.5		16.6mm	11mm	20mm	11mm	20mm	
ting	Pow	er supply			12-24V DC ±10% / Rip		±10% / Ripp	le 10% max.				
Ra	Current			max.	70mA			max.	80mA max	80mA max	80mA max	
	consumpti	on Receiver	100mA	max. *	65mA			max. *	70mA max. *		70mA max. *	
	Output mode Models with n			NPN open collector Rating: sink current 100 mA (30 VDC max.) with model Nos. ending with X-PNE have PNP open collector output; source current: 100 mA max.								
	Opera	ation mode	Activated when light beams of all axes are received (deactivated when light beam of any axis is block									
		Response time Light blocking :5ms max. Light reception 8ms max. Light blocking :3ms max. Light reception 4ms max			Light reception 4ms max.	Light blocking :5ms max. Light reception 8ms max.						
	Light source (wavelength) Infrared LED (860nm)											
	Indicator		Transmitter: Power indicator (green LED)									
	l in	dicator	Receiver: Power indicator (green LED) / Operation indicator (OrangeLED)									
_	Short ci	rcuit protection	Provided									
Specification	M	laterial	Case body: Aluminum / Caps at ends: glass fiber filled PBT									
ific	Connection		Permanently attached cord (Outer dimension: dia.4) Cord length: 3 m									
bec	Connection	Cord: with two 0.3 mm2 cores, gray (transmitter) or with three 0.3 mm2 cores black (receiver) covering										
S		Mass	About 130 g (transmitter/receiver) About 130 g (transmitter/receiver) About 130 g (transmitter/receiver)									
	Ac	cessory	Operation manual (Note) Mounting brackets are not provided									
	1	Notes	*The receiver current consumption shown is for 12 VDC. When the voltage is 24 VDC, the consumption is reduced to about 60%. *1 "-D" types, or models deactivated when light beams of all axes are received, are also available.									

Environmental Specification

Environment	Ambient light	5,000lx max.				
	Ambient temperature	-10 - +55°C (non-freezing)				
	Ambient humidity	35-85%RH (non-condensing)				
	Protective structure	IP67				
	Vibration	10-55 Hz / 1.5 mm amplitude / 2 hours each in 3 directions				
	Shock	500 m/s ² / Twice each in 3 directions				
	Dielectric withstanding	500 VAC for 1 minute				
	Insulation resistance	500 VDC, 20 MΩ or higher.				

• Applicable power supply unit

PS Series High capacity of 200 mA at 12 VDC



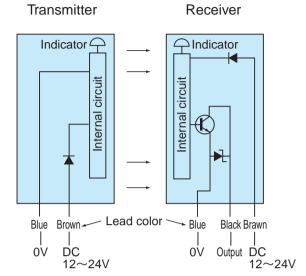
(General-purpose type) PS3N

PS3N-SR

(Multifunctional type) PS3F

PS3F-SR

Input/Output Circuit and Connection



The output transistor turns off when load short circuits or overload occurs. Check the load and turn the power back on

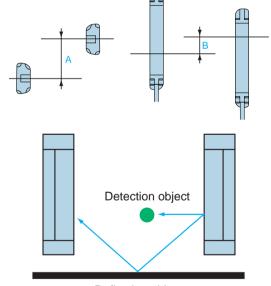
Setting

Install the transmitter and receiver face-to-face.

Swivel the transmitter and receiver vertically and horizontally to install them at the center of the area in which the operation indicator (orange LED) is illuminated for the individual direction.

The tightening torque for installing the sensor (with M4 screws) should be up to 0.6 N·m.

- Displacement in the A direction may be up to ±30mm.
 Displacement in the B direction should be within ±10mm.
- If the transmitter and receiver are too closely installed to each other or light axes are misaligned, the output may be unstable. When the light axes are aligned, the operation returns to normal.
- Any reflecting object (wall, floor, machine, etc.) within the
 effective range between the transmitter and receiver may
 allow the light of the sensor to go around the detection object,
 which is supposed to block the light, and reach the receiver.
 Choose the installation location carefully.
 - Any glossy object such as a coated surface in the surrounding area must be at least 100mm away for the distance setting of within 1m and 150mm away for the distance setting of over 1m.
- Use caution with interference when installing sensor adjacently.



Reflecting object

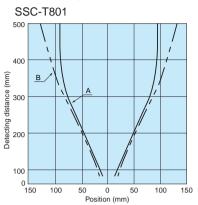
For Correct Use

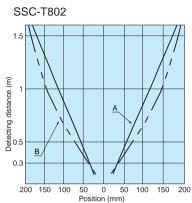


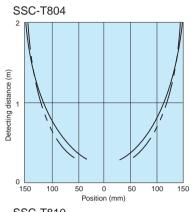
- Be sure to follow the instructions in the operation manual provided for correct use of the product.
- This sensor cannot be used as a press safety device or other safety device for protection of human body that requires conformity to domestic or overseas standards or certification concerning protection of human body. Use for such purposes may lead to death or serious injury in the unlikely event of failure.
- This sensor is intended for detection of ingress of human body or object passing through an arbitrary point not involving protection of human body or safety.
- When using this sensor for safety purposes, ensure safe operation of the system as a whole including detection and control.

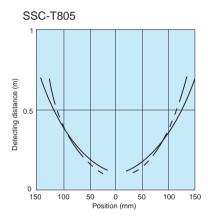
Characteristics (Typical Example)

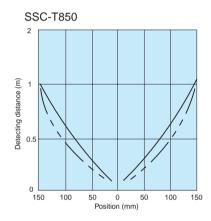
Parallel displacement characteristics

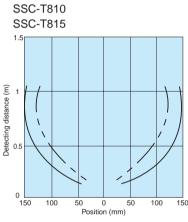


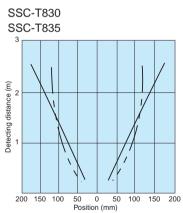


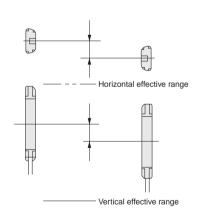






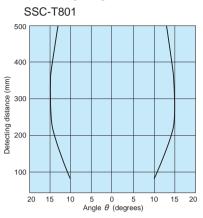


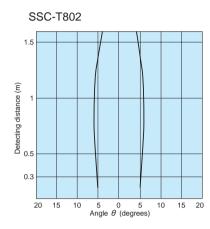


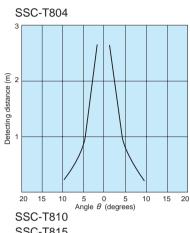


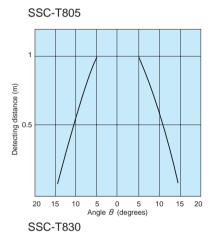
■ Characteristics (Typical Example)

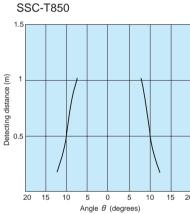
Operating angle characteristics

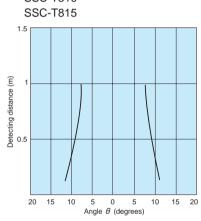


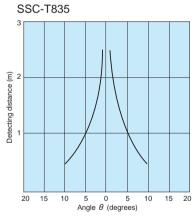


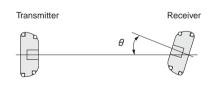






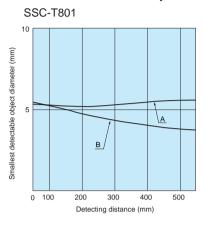


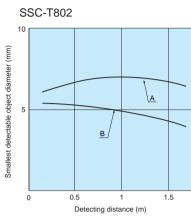


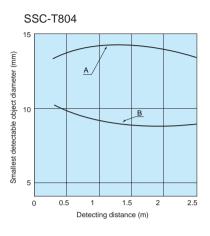


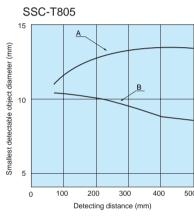
■ Characteristics (Typical Example)

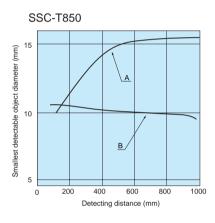
• Smallest detectable object diameter characteristics

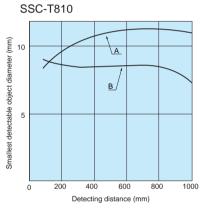


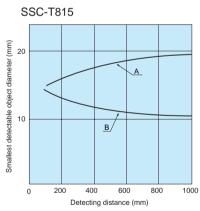


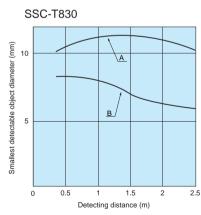


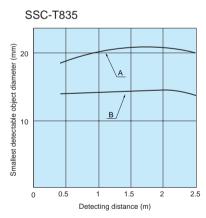


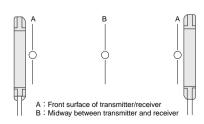












Dimensions (in mm)

