# N1540 Indicator Registers Table

### 1.1 SERIAL COMMUNICATION

The optional serial interface RS485 allows to address up to 247 indicators in a network communicating remotely with a host computer or master indicator.

#### **RS485 Interface**

- Compatible line signals with RS485 standard.
- 3 wire connection from master to up to 31 slaves indicators in a multidrop bus. It is possible address 247 nodes with multiple outputs converters.
- Maximum communication distance: 1000 meters
- The RS485 signals are:

D1 = D: Bidirectional data line.

 $D0 = \overline{D}$ : Bidirectional inverted data line.

C = GND: Optional connection which left communication better.

### **General Characteristics**

- · Optically isolated serial interface.
- Programmable baud rate: 1200, 2400, 4800, 9600, 19200, 38400, 57600 and 115200 bps.
- Data Bits: 8
- Parity: None, Even or Odd.
- Stop Bits: 1

### **Communication Protocol**

The MOSBUS RTU slave is implemented, available in most SCADA softwares in the market.

All configurable parameters can be accessed (for reading or writing) through the Registers Table. Broadcast commands are supported as well (address 0).

The available Modbus commands are:

03 - Read Holding Register

05 - Force Single Coil

06 - Preset Single Register

16 - Preset Multiple Register

The registers are arranged in a table in such a way that several registers can be read in the same request.

# 1.2 CONFIGURATION OF SERIAL COMMUNICATION PARAMETERS

Three parameters must be configured in the device for serial communication:

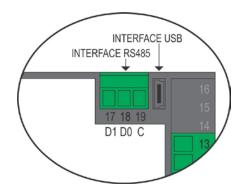
**bRud**: Baud rate. All devices with same baud rate.

**Rddr**: Device communication address. Each device must have an

exclusive address.

Prty: Parity.

### 1.3 CONNECTIONS



### 1.4 REGISTERS TABLE

Equivalent to the holding registers (referenced as 4X).

The holding registers are basically a list of the internal indicator parameters. All registers above address 12 can be read or written. The registers up to this address in more are read only. Please verify each case. Each table parameter is a 16 bits two complement signed word.

Holding Registers	Parameter	Register Description
0000	ALrF	Differential alarm reference.  Maximum range: <b>SPLL</b> to <b>SPHL</b> (or the sensor span)
0001	PV	Read: Process Variable.  Write: Not allowed.  In case of temperature reading, the value read is always multiplied by 10, independently of dPPo value.
0002	Reserved	Internal use
0003	Reserved	Internal use
0004	Display Value	Read: Current value shown on display. Write: Current value shown on display. Range: -2000 to 30000. The range depends on the displayed parameter.
0005	Prompt index	Read: Current prompt position in the parameters flowchart.  Write: no allowed. Range: 0000h to 060Ch  Prompt number format: XXYYh, where:  XX → menu cycle number  YY → prompt number
0006	Status Word 1	Read: Status bits. Write: no allowed. Valor lido: See Table 2.
0007	Software Version	Read: The firmware version of indicator. If V1.00, the read value will be 100. Write: not allowed.
0008	ID	Read: indicator identification number: <b>69</b> Write: not allowed.
0009	Status Word 2	Read: Status bits. See <b>Table 2</b> . Write: no allowed.
0010	Status Word 3	Read: Status bits. See <b>Table 2</b> . Write: no allowed.
0011~0015	Reserved	Internal use
0016	FrE9	Read/Write: Mains frequency. Range: 0 – 1 (60/50Hz)
0017	Reserved	
0018	FLEr	Read/Write: PV digital filter gain. Range: 0 – 20
0019	Reserved	Internal use
0020	SP LE	Controls the presence of the parameter SPA1 in the indicator operation cycle.  0→ Disables;  1→ Enables;
0021	SP2.E	Controls the presence of the parameter Alarm 2 in the indicator operation cycle.  0→ Disables;  1→ Enables;
0022	Reserved	Internal use
0023	Serial number H	Serial number first four digits. Range: 0 to 9999. Read only.
0024	Serial number L	Serial number last four digits. Range: 0 to 9999. Read only.
0025	Reserved	Internal use
0026	inLL	Defines the minimum PV indication value for analog input types (used to scale the analog inputs).

0027	InHL	Defines the indication higher limit of the PV indication (used to scale the analog inputs).
0028	Reserved	Internal use
0029	oFF5	PV Offset (Process Variable). Range: from <b>SPLL</b> to <b>SPhL</b>
0030	dPPo	PV decimal point position. Range: 0 to 3 $0 \rightarrow X.XXX; 1 \rightarrow XX.XX; 2 \rightarrow XXX.X; 3 \rightarrow XXXX$
0031	SPA I	Alarm 1 Setpoint.
0032	SP.A.2	Alarm 2 Setpoint.
0033	Reserved	Internal use
0034	Reserved	Internal use
0035	FuR I	Alarm function. Range: 0 to 8. $0 \rightarrow \mathbf{oFF}$ ; $1 \rightarrow \mathbf{Lo}$ ; $2 \rightarrow \mathbf{h}$ ; $3 \rightarrow \mathbf{d}$ $\mathbf{iF}$ ;
0036	FuA2	4→d :FL; 5→d :Fh; 6→ :Err;
0037~0038	Reserved	Internal use
0039	HYR I	Alarm 1 Hysteresis. Range: 0 to 9999 (0.00 to 99.99 %)
0040	HYR2	Alarm 2 Hysteresis. Range: same as in <b>HYR 1</b> .
0041	Reserved	Internal use
0042	Reserved	Internal use
0043	<b>E</b> YPE	PV input type. Range: 0 to 22. See operation manual.
0044	Addr	Communication slave address. Range: 1 to 247.
0045	ЬRud	Communication <i>Baud-Rate</i> . Range: 0 to 7 $0 \rightarrow 1200$ ; $1 \rightarrow 2400$ ; $2 \rightarrow 4800$ ; $3 \rightarrow 9600$ ; $4 \rightarrow 19200$ ; $5 \rightarrow 32400$ ; $6 \rightarrow 57600$ ; $7 \rightarrow 115200$ .
0046~0049	Reserved	Internal use
0050	bla i	Alarm 1 power-up inhibit.
0051	PL45	Range: 0→no; 1→yes.
0052	Reserved	Internal use
0053	Reserved	Internal use
0054	Key	Key simulation.  1 → Key press P  2 → Key press F1  4 → Key press F2  8 → Key press < 9 → Cycle progress
0055~0066	Reserved	Internal use
0067	un IE	Temperature unit. Range: 0 to 1 0→°C; 1→°F.
0068~0074	Reserved	Internal use
0075	Calibration PV First	Enter the first input value currently applied in the PV input for calibration purposes.
0076	Calibration PV End	Enter the end input value currently applied in the PV input for calibration purposes.
0077~0080	Reserved	Internal use
0081	FLSh	Enables the top display blinking as a function of the selected alarm.  0→ Disables  1→ Enables
0082~0085	Reserved	Internal use
0086	r5tr	Restores original default calibration. Range: 0 to 1; 0→ do not restore 1→ restore calibration

0087	Reserved	Internal use
0088	88 Prot	Password protection level. Range: 1 to 3.
0088		Check instruction manual for further details.
0089	PrŁY	Serial communication parity. Range: 0 to 2.
0009		0-> no parity; 1 - > even parity; 2 - > odd parity;

### 1.5 STATUS WORDS

Register	Value Format
Status Word 1	bit 0 - Alarm 1 (0-inactive; 1-active)
	bit 1 - Alarm 2 (0-inactive; 1-active)
	bit 2~7 - Reserved
	bit 8 - Hardware detection value
	bit 9 - Hardware detection value
	bit 10~15 - Reserved
Status Word 2	bit 0 - Reserved
	bit 1 - Reserved
	bit 2 - Reserved
	bit 3 - Reserved
	bit 4 - Reserved
	bit 5 - Alarm 1 power-up inhibit (0-no; 1-yes)
	bit 6 - Alarm 2 power-up inhibit (0-no; 1-yes)
	bit 7 - Reserved
	bit 8 - Reserved
	bit 9 - Unit (0-°C; 1-°F)
	bit 10~15 - Reserved
Status Word 3	bit 0 – Very low PV conversion (0-no; 1-yes)
	bit 1 – Negative conversion after calibration (0-no; 1-yes)
	bit 2 – Very high PV conversion (0-no; 1-yes)
	bit 3 – Exceeded linearization limit (0-no; 1-yes)
	bit 4 – Very high Pt100 cable resistance (0-no; 1-yes)
	bit 5 – Self zero conversion out of range (0-no; 1-yes)
	bit 6 – Self span conversion out of range (0-no; 1-yes)
	bit 7~15 - Reserved

Table 2 - Values of Status Words

Writing to a digital output is only allowed if the corresponding alarm is configured as "**oFF**".

Coil Status	Output description
0	Output 1 Status (ALM1)
1	Output 2 Status (ALM2)

## 1.6 EXCEPTION RESPONSES – ERROR CONDITIONS

The MODBUS RTU protocol checks the CRC in the data blocks received.

Reception errors are detected by the CRC, causing the indicator to discard the packet, not sending any reply to the master.

After receiving an error-free packet, the indicator processes the packet and verifies whether the request is valid or not, sending back an exception error code in case of an invalid request. Response frames containing error codes have the most significant bit of the Modbus command set (the value 80H is added to the response).

If a WRITE command sends an out-of-range value to a parameter, the indicator will clamp the value to the parameter range limits, replying with a value that reflects these limits (maximum or minimum value allowed for the parameter).

The indicator ignores broadcast READ commands; the indicator processes only broadcast WRITE commands.

Error Code	Error Description
01	Invalid command or not available
02	Invalid Register Number or out of range
03	Invalid Register Quantity or out of range

Table 3 - Exception response error codes