N1540 Indicator Registers Table – V2.0x

1.1 SERIAL COMMUNICATION

The optional serial interface RS485 allows to address up to 247 indicators in a network communicating remotely with a host computer or master indicator.

RS485 Interface

- Compatible line signals with RS485 standard.
- 3 wire connection from master to up to 31 slaves indicators in a multidrop bus. It is possible address 247 nodes with multiple outputs converters.
- Maximum communication distance: 1000 meters
- The RS485 signals are:

D1 = D: Bidirectional data line.

 $D0 = \overline{D}$: Bidirectional inverted data line.

C = GND: Optional connection which left communication better.

General Characteristics

- Optically isolated serial interface.
- Programmable baud rate: 1200, 2400, 4800, 9600, 19200, 38400, 57600 and 115200 bps.
- Data Bits: 8
- · Parity: None, Even or Odd.
- Stop Bits: 1

Communication Protocol

The MOSBUS RTU slave is implemented, available in most SCADA softwares in the market.

All configurable parameters can be accessed (for reading or writing) through the Registers Table. Broadcast commands are supported as well (address 0).

The available Modbus commands are:

03 - Read Holding Register

05 - Force Single Coil

06 - Preset Single Register

16 - Preset Multiple Register

The registers are arranged in a table in such a way that several registers can be read in the same request.

1.2 CONFIGURATION OF SERIAL COMMUNICATION PARAMETERS

Three parameters must be configured in the device for serial communication:

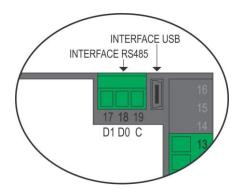
bRud: Baud rate. All devices with same baud rate.

Rddr: Device communication address. Each device must have an

exclusive address.

Prty: Parity.

1.3 CONNECTIONS



1.4 REGISTERS TABLE

Equivalent to the holding registers (referenced as 4X).

The holding registers are basically a list of the internal indicator parameters. All registers above address 12 can be read or written. The registers up to this address in more are read only. Please verify each case. Each table parameter is a 16 bits two complement signed word.

Holding Registers	Parameter	Register Description
		Read: Process Variable.
0000	PV	Write: Not allowed.
0000	1 V	In case of temperature reading, the value read is always multiplied by 10,
		independently of dPPa value.
0001	PVmin	Read: Minimum value of PV. Write: not allowed.
0002	Pvmax	Read: Maximum value of PV.
		Write: not allowed.
0003		Reserved
	Display Value	Read: Current value shown on display.
0004		Write: Current value shown on display. Range: -2000 to 30000. The range
		depends on the displayed parameter.
		Read: Current prompt position in the
		parameters flowchart. Write: no allowed. Range: 0000h to 060Ch
0005	Prompt index	Prompt number format: XXYYh, where:
		XX→ menu cycle number
		YY→ prompt number
		Read: Status bits.
0006	Status Word 1	Write: no allowed.
		Read Value: See Table 2 .
0007	Software Version	Read: The firmware version of indicator. If V1.00, the read value will be 100.
0007	Software version	Write: not allowed.
		Read: indicator identification number: 69
8000	ID	(45h)
		Write: not allowed.
0009	Status Word 2	Read: Status bits. See Table 2 . Write: no allowed
	Status Word 3	Read: Status bits. See Table 2 .
0010		Write: no allowed.
		Key simulation.
		$1 \rightarrow$ Key press P - (go to next level of
	Key	parameters). 2→ Key press F1
0011		4→ Key press F2
		8→ Key press <
		$9 \rightarrow$ Key press P - (go to next level of
		cycle).
0012	Serial Number H	First four digits of Serial Number. Range: 0 to 9999. Read only
		Last four digits of Serial Number.
0013	Serial Number L	Range: 0 to 9999. Read only
0014~0016	Reserved	Internal use
		Differential alarm reference.
0017	ALrF	Maximum range: SPLL to SPHL (or the
0040		sensor span)
0018	5P.R I	Alarm setpoint.
0019	5P.R2	
0020	5P.R3	
0021	5P.R4	
0022	FuR I	Alarm function. Range: 0 to 8
0023	FuR2	$0 \rightarrow \mathbf{o} \mathbf{F} \mathbf{F}; 1 \rightarrow \mathbf{L} \mathbf{o};$ $2 \rightarrow \mathbf{h} \mathbf{i};$ $3 \rightarrow \mathbf{d} \mathbf{i} \mathbf{F} \mathbf{i};$ $5 \rightarrow \mathbf{d} \mathbf{i} \mathbf{F} \mathbf{h};$
0024	FuR3	$3\rightarrow d$ if; $4\rightarrow d$ if L; $5\rightarrow d$ if h; $6\rightarrow iErr$:
0025	FuR4	,

2000		
0026	нул і	Alarm hysteresis.
0027	HYA2	
0028	ЕЯ.ЕН	
0029	РА <u>г</u> н	
0030~0037	Reserved	Internal use
0038	ЫДЯ І	Alarm power-up inhibit
0039	PT'45	0→ No
0040	Ы ЯЗ	1→ Yes
0041	ЫДЯЧ	
0042	SP LE	Controls the presence of the parameter SPA1 in the indicator operation cycle. 0→ Disables (hides SPA1);
		1→ Enables (shows SPA1); Controls the presence of the parameter
0043	SP2.E	SPA2 in the indicator operation cycle. 0→ Disables (hides SPA2);
		1→ Enables (shows SPA2);
0044	FLSh	Allows visual signalization of an alarm occurrence by flashing the indication of PV in the operation level. 0→ Disables
0045~0049	Reserved	1→ Enables Internal use
0043 0043	rteserveu	
0050	FALE	PV input type. Range: 0 a 22. See operation manual.
0051	un it	Temperature unit. Range: 0 a 1 0 = °C; 1 = °F.
0052	dP.P.o	PV decimal point position. Range: 0 to 3 $0 \rightarrow X.XXX; 1 \rightarrow XX.XX; 2 \rightarrow XXX.X; 3 \rightarrow XXXX$
0053	FLEr	Read/Write: PV digital filter gain. Range: 0 – 20
0054	FrE9	Read/Write: Mains frequency. Range: 0 = 60 Hz / 1 = 50Hz
0055	Reserved	Internal use
0056	oFF5	PV Offset (Process Variable). Range: from 5PLL to 5PHL
0057	inLL	Defines the minimum PV indication value for analog input types (used to scale the analog inputs).
0058	inHL	Defines the indication higher limit of the PV indication (used to scale the analog inputs).
0059-0066	Reserved	Internal use
0067	Rddr	Communication slave address. Range: 1 to 247
0068	bRud	Communication <i>Baud-Rate</i> . Range: 0 to 7 0→1200; 1→2400; 2→4800; 3→9600; 4→19200; 5→32400; 6→57600; 7→115200.
0069	Prty	Serial communication parity. Range: 0 to 2. 0-> no parity; 1 - > even parity; 2 - > odd parity;
0070~0079	Reserved	Internal use
0800	Calibration PV First	Enter the low input value currently applied in the PV input for calibration purposes.
0081	Calibration PV End	Enter the high input value currently applied in the PV input for calibration purposes.

0082	82 r5 £r	Restores original default calibration. Range: 0 to 1; 0 → do not restore 1 → restore calibration
0083	Reserved	Internal use
0084	Prot	Password protection level. Range: 1 to 3. Check instruction manual for further details.

1.5 STATUS WORDS

Register	Value Format
Status Word 1	bit 0 - Alarm 1 (0-inactive; 1-active)
	bit 1 - Alarm 2 (0-inactive; 1-active)
	bit 2~7 - Reserved
	bit 8 - Hardware detection value
	bit 9 - Hardware detection value
	bit 10~15 - Reserved
Status Word 2	bit 0 - Reserved
	bit 1 - Reserved
	bit 2 - Reserved
	bit 3 - Reserved
	bit 4 - Reserved
	bit 5 - Alarm 1 power-up inhibit (0-no; 1-yes)
	bit 6 - Alarm 2 power-up inhibit (0-no; 1-yes)
	bit 7 - Reserved
	bit 8 - Reserved
	bit 9 - Unit (0-°C; 1-°F)
	bit 10~15 - Reserved
Status Word 3	bit 0 – Very low PV conversion (0-no; 1-yes)
	bit 1 – Negative conversion after calibration (0-no; 1-yes)
	bit 2 – Very high PV conversion (0-no; 1-yes)
	bit 3 – Exceeded linearization limit (0-no; 1-yes)
	bit 4 – Very high Pt100 cable resistance (0-no; 1-yes)
	bit 5 – Self zero conversion out of range (0-no; 1-yes)
	bit 6 – Self span conversion out of range (0-no; 1-yes)
	bit 7~15 - Reserved

Table 2 - Values of Status Words

Writing to a digital output is only allowed if the corresponding alarm is configured as " ${\it aFF}$ ".

Coil Status	Output description
0	Output 1 Status (ALM1)
1	Output 2 Status (ALM2)

1.6 EXCEPTION RESPONSES – ERROR CONDITIONS

The MODBUS RTU protocol checks the CRC in the data blocks received.

Reception errors are detected by the CRC, causing the indicator to discard the packet, not sending any reply to the master.

After receiving an error-free packet, the indicator processes the packet and verifies whether the request is valid or not, sending back an exception error code in case of an invalid request. Response frames containing error codes have the most significant bit of the Modbus command set (the value 80H is added to the response).

If a WRITE command sends an out-of-range value to a parameter, the indicator will clamp the value to the parameter range limits, replying with a value that reflects these limits (maximum or minimum value allowed for the parameter).

The indicator ignores broadcast READ commands; the indicator processes only broadcast WRITE commands.

Error Code	Error Description
01	Invalid command or not available
02	Invalid Register Number or out of range
03	Invalid Register Quantity or out of range

Table 3 - Exception response error codes