# N1100 / N2000 / N3000

### Communication Protocol - V3.0x A

#### 1. SERIAL COMMUNICATION

#### 1.1 COMMUNICATION INTERFACE

The optional serial interface RS485 allows to address up to 247 controllers in a network communicating remotely with a host computer or master controller.

### RS485 Interface

- Compatible line signals with RS485 standard
- 2 wire connection from master to up to 31 slaves indicators in a multidrop bus. It is possible address 247 nodes with multiple outputs converters.
- Maximum communication distance: 1000 meters
- The RS485 signals are:

D1 = D: Bidirectional data line.

 $D0 = \overline{D}$ : Bidirectional inverted data line.

C = GND: Optional connection which left communication better.

#### **General Characteristics**

- Optically isolated serial interface
- Velocity programmable: 1200 a 11.200
- Data Bits: 8
- Parity: None
- Stop Bits: 1

# Communication Protocol

The MOSBUS RTU slave is implemented, available in most SCADA softwares in the market

All configurable parameters can be accessed (for reading or writing) through the Registers Table. Broadcast commands are supported as well (address 0).

The available Modbus commands are:

- 03 Read Holding Register
- 05 Force Single Coil (Force Digital Output state)
- 06 Preset Single Register

The registers are arranged in a table in such a way that several registers can be read in the same request.

# 1.2 CONFIGURATION OF SERIAL COMMUNICATION PARAMETERS

Two parameters must be configured in the device for serial communication:

**bRud**: Baud rate. All devices with same baud rate.

**Rddr**: Device communication address. Each device must have an exclusive address.

# 1.3 REGISTERS TABLE

Equivalent to the registers referenced as 4X.

The holding registers are basically a list of the internal indicator parameters. All registers above address 12 can be read or written. The registers up to this address in more are read only. Please verify each case. Each table parameter is a 16 bits two complement signed word.

Holding Registers	Parameter	Register Description
0000	Active SV	Read: Active control SV (main SV, from ramp and soak or from remote SV). Write: to main SV Range: from <b>5PLL</b> to <b>5PHL</b> .
0001	PV	Read: Process Variable Write: not allowed. Range: From <b>5PLL</b> to <b>5PHL</b> . The <b>dPPo</b> prompt gives the decimal point position.
0002	MV	Read: Output Power in automatic or manual mode. Write: not allowed. See address 29. Range: 0 to 1000 (0.0 to 100.0%).
0003	-	Reserved.
0004	Display value	Read: Current value shown on display. Write: Current value shown on display. Range: -1999 to 9999. The range depends on the displayed parameter.

index  Write: not allowed. Range: 0000h to 060Ch Prompt number format: XXYYh, where: XX→menu cycle number (see operation manual) YY→prompt number (index).  Read: Status bits. See table 2 Write: not allowed.  O007  Software Version  Read: The firmware version of controller. If V1.00, the reavalue will be 100. Write: not allowed.  O008  ID  Read: controller identification number. Write: not allowed.  Values: 1 − N1100; 2 - N2000 / N3000 Other values: special instruments.  O009  Status Word 2  Write: not allowed.  O010  Status Word 3  Read: Status bits. See table 2. Write: not allowed.  O011  Ir  Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012  Derivative Time (in seconds). Range: 0 to 250  Proportional Band (in percentage)
Prompt number format: XXYYh, where: XX→menu cycle number (see operation manual) YY→prompt number (index).  Read: Status bits. See table 2 Write: not allowed.  Read: The firmware version of controller. If V1.00, the reavalue will be 100. Write: not allowed.  Read: Controller identification number. Write: not allowed.  Values: 1 - N1100; 2 - N2000 / N3000 Other values: special instruments.  Read: Status bits. See table 2. Write: not allowed.  Read: Status bits. See table 2. Write: not allowed.  Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  Derivative Time (in seconds). Range: 0 to 250
XX→menu cycle number (see operation manual) YY→prompt number (index).  Read: Status bits. See table 2 Write: not allowed.  Read: The firmware version of controller. If V1.00, the reavalue will be 100. Write: not allowed.  O008  ID  Read: controller identification number. Write: not allowed.  Values:  1 - N1100; 2 - N2000 / N3000 Other values: special instruments.  O009  Status Word 2 Write: not allowed.  O010  Status Word 3  Read: Status bits. See table 2. Write: not allowed.  O011  Ir  Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012  dt  Derivative Time (in seconds). Range: 0 to 250
YY→prompt number (index).  Nead: Status bits. See table 2 Write: not allowed.  Nead: The firmware version of controller. If V1.00, the reavalue will be 100. Write: not allowed.  Nead: Controller identification number. Write: not allowed.  Nalues:  1 - N1100; 2 - N2000 / N3000 Other values: special instruments.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.  Nead: Status bits. See table 2. Write: not allowed.
O006 Status Word 1  Read: Status bits. See table 2 Write: not allowed.  Read: The firmware version of controller. If V1.00, the real value will be 100. Write: not allowed.  O008 ID Read: controller identification number. Write: not allowed.  Values: 1 - N1100; 2 - N2000 / N3000 Other values: special instruments.  O009 Status Word 2 Write: not allowed.  O010 Status Word 3 Read: Status bits. See table 2. Write: not allowed.  O011 Ir Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012 dt Derivative Time (in seconds). Range: 0 to 250
Word 1 Word 1 Write: not allowed.  Read: The firmware version of controller. If V1.00, the real value will be 100. Write: not allowed.  O008  ID Read: Controller identification number. Write: not allowed. Values: 1 - N1100; 2 - N2000 / N3000 Other values: special instruments.  O009 Status Word 2 Write: not allowed.  O010 Status Word 3 Write: not allowed.  Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012  dt Derivative Time (in seconds). Range: 0 to 250
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Version  Version  Version  Version  Version  Version  Value will be 100.  Write: not allowed.  Read: controller identification number.  Write: not allowed.  Values:  1 - N1100; 2 - N2000 / N3000  Other values: special instruments.  Read: Status bits. See table 2.  Write: not allowed.  Oo10  Status Word 2  Write: not allowed.  Oo11  Ir  Integral Rate (in repetitions/min)  Range: 0 to 3000 (0.00 to 30.00)  Oo12  dt  Derivative Time (in seconds). Range: 0 to 250
Write: not allowed.  O008  ID  Read: controller identification number. Write: not allowed.  Values:  1 - N1100; 2 - N2000 / N3000 Other values: special instruments.  Read: Status bits. See table 2. Write: not allowed.  O010  Status Word 3  Read: Status bits. See table 2. Write: not allowed.  O011  Ir  Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012  dt  Derivative Time (in seconds). Range: 0 to 250
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Write: not allowed.  Values:  1 – N1100; 2 - N2000 / N3000  Other values: special instruments.  0009 Status Word 2 Write: not allowed.  0010 Status Word 3 Read: Status bits. See table 2. Write: not allowed.  0011 Ir Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  0012 dt Derivative Time (in seconds). Range: 0 to 250
Values:
1 – N1100; 2 - N2000 / N3000 Other values: special instruments.  Read: Status bits. See table 2. Write: not allowed.  Status Word 3 Write: not allowed.  Read: Status bits. See table 2. Write: not allowed.  Read: Status bits. See table 2. Write: not allowed.  Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  Derivative Time (in seconds). Range: 0 to 250
0009 Status Word 2 Read: Status bits. See table 2. Write: not allowed.  0010 Status Word 3 Read: Status bits. See table 2. Write: not allowed.  0011 Ir Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  0012 db Derivative Time (in seconds). Range: 0 to 250
Word 2 Write: not allowed.  O010 Status Word 3 Read: Status bits. See table 2. Write: not allowed.  O011  Ir Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012  dE Derivative Time (in seconds). Range: 0 to 250
Write: not allowed.  O010 Status Word 3 Read: Status bits. See table 2. Write: not allowed.  O011 Ir Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  O012 dL Derivative Time (in seconds). Range: 0 to 250
Word 3 Write: not allowed.  10011 Ir Integral Rate (in repetitions/min) Range: 0 to 3000 (0.00 to 30.00)  10012 Derivative Time (in seconds). Range: 0 to 250
Write: not allowed.
Range: 0 to 3000 (0.00 to 30.00)
Range: 0 to 3000 (0.00 to 30.00)  0012
Derivative Time (in Seconds). Range. 0 to 250
0013 <b>Pb</b> Proportional Band (in percentage)
Range: 0 to 5000 (0.0 to 500.0)
0014 <b>ŁŁR5</b> Program time base.
0→ seconds
1→ minutes
0015 CE Cycle Time (PWM, in seconds)
Range: 5 to 1000 (0.5 to 100.0)
0016 - Reserved.
0017
On/Off Control Hysteresis (in selected type engineering unit).  Range: 0 to <b>SPHL</b> - <b>SPLL</b>
0018 - Reserved.
0019 <b>auLL</b> Output Low Limit (minimum output power)
Range: 0 to 1000 (0.0 to 100.0%).
0000
Output High Limit (minimum output power)  Range: 0 to 1000 (0.0 to 100.0%).
0001 8 5
N2000 only.  Auto/Man key Enable – 👺
1 $\rightarrow$ Key enabled 0 $\rightarrow$ Key disabled
0022 <b>FFunc</b> Allows defining a function for the F key. The available N200
and N3000.  0 → Not used.
7 → Controller start/stop.
8 → Select remote SP. 9 → Ramp and soak hold.
9 → Ramp and soak noid. 10 → Enable ramp and soak profile 1.
0023 Serial Serial Number High (Upper display).
Number H Range: 0 to 9999. Read only
0024 Serial Serial Number Low (Lower display).
Number L Range: 0 to 9999. Read only
0025 SV Control Setpoint (Prompt Setpoint).
Range: from <b>SPLL</b> to <b>SPHL</b> .
0026 <b>SPLL</b> Setpoint Low limit.
Range: minimum value depends on the input type selected in
EYPE (see op. Manual) to SPHL.

0027		T
1	5PHL	Setpoint High limit.
		Range: minimum value is <b>SPLL</b> and maximum depends on the
		input type selected in <b>LYPE</b> (see op. Manual).
0028	Manual	
0026	MV	Manual output power (in percentage)
	1010	Range: 0 to 1000 (0.0 to 100.0%)
0029	oFF5	PV offset
	· · · · · ·	
		Range: from <b>SPLL</b> to <b>SPHL</b> .
0030	dPPo	PV decimal point position
		Range: 0 to 3
		$0 \rightarrow X.XXX; 1 \rightarrow XX.XX; 2 \rightarrow XXX.X; 3 \rightarrow XXXX$
0031	5P.A I	Range: The minimum value is at <b>5PLL</b> for non-differential alarm
0032	SPA2	or <b>SPLL - SPLH</b> for differential alarm
0033	SPA3	
0034	5РЯЧ	The maximum value is at <b>5PHL</b> for non-differential alarm or at <b>5PHL - 5PLL</b> for differential alarm.
		JING - JIEE IOI UIII elelitidi alaitti.
0035	FuR I	Alarm Function. Range: 0 to 7
0036	FuR2	-0→oFF
0037	FuR3	1→ <b>1</b> Err
0038	FuR4	2→ <b>r5</b>
		3→ <b>Lo</b>
		3→L0 4→H 1
		5→ <b>d IFL</b>
		5→6 IFH
		0→ <b>a</b> irn 7→ <b>d iF</b>
0039	HYR I	
0039	HYR2	Alarm Hysteresis. Range: 0 to 9999 (0.00 to 99.99%)
0040	HYR3	1
0041	HYRY	1
0042	LYPE	January Toma
0043	Carc	Input Type.
		- (J) -110 to 950 °C / -166 to 1742 °F
		<b>Lc P</b> - (K) -150 to 1370 °C / -238 to 2498 °F
		<b>Lc L</b> - (T) -160 to 400 °C / -256 to 752 °F
		<b>Lc n</b> - (N) -270 to 1300 °C / -454 to 2372 °F
		<b>Lc r</b> - (R) -50 to 1760 °C / -58 to 3200 °F
		<b>Lc 5</b> - (S) -50 to 1760 °C / -58 to 3200 °F
		<b>Lc b</b> - (B) 400 to 1800 °C / 752 to 3272 °F
		<b>Lc E</b> - (E) -90 to 730 °C / -130 to 1346 °F
		<b>PL</b> - Pt100 -200 to 850 °C / -328 to 1562 °F
		<b>L.0.50</b> - (0-50 mV) -1999 to 9999
		<b>L4.20</b> - (4-20 mA) -1999 to 9999
		<b>L.0.5</b> - (0-5 V) -1999 to 9999
		<b>L.D. 1D</b> - (0-10 V) -1999 to 9999
		<b>59rL</b> - (square root) -1999 to 9999
0044	Rddr	Communication slave address
		Range: 1 to 247
0045	Pynq	Comunication Baud Rate. Range: 0 to 7
l		· · · · · · · · · · · · · · · · · · ·
i		0→1200
		0→1200 1→2400
		1→2400
		1→2400 2→4800
		1→2400 2→4800 3→9600
		1→2400 2→4800 3→9600 4→19200
		$1 \rightarrow 2400$ $2 \rightarrow 4800$ $3 \rightarrow 9600$ $4 \rightarrow 19200$ $5 \rightarrow 32400$
		1→2400 2→4800 3→9600 4→19200 5→32400 6→57600
00/46	0.4-	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200
0046	Ruto	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600
0046	Ruto	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.
0047	LUU	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.
0047	run Rct	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.
0047 0048 0049	run Act Atun	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.
0047 0048 0049 0050	run Act Atun BLA 1	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→no; 1→yes.
0047 0048 0049 0050 0051	Fun Act Atun BLA 1 BLA2	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→reverse; 1→direct.
0047 0048 0049 0050 0051 0052	REE REUN BLR I BLR 2 BLR 3	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→no; 1→yes.
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→no; 1→yes.
0047 0048 0049 0050 0051 0052	REE REUN BLR I BLR 2 BLR 3	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→reverse; 1→direct.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→reverse; 1→direct.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→reverse; 1→direct.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.  Key press remote action. Range: 0 to 9 1: tecla P
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→reverse; 1→direct.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→reverse; 1→direct.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.  Key press remote action. Range: 0 to 9 1: tecla P
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→reverse; 1→direct.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.  Key press remote action. Range: 0 to 9 1: tecla P 2: tecla ∧ 4: tecla ∨
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→no; 1→yes.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.  Key press remote action. Range: 0 to 9 1: tecla P 2: tecla ∧ 4: tecla ∨ 8: tecla <
0047 0048 0049 0050 0051 0052 0053	REE REUM BLR 1 BLR 2 BLR 3 BLR 4	1→2400 2→4800 3→9600 4→19200 5→32400 6→57600 7→115200  Control Mode. Range: 0→manual; 1→automatic.  Enable control. Range: 0→no; 1→yes.  Control action. Range: 0→no; 1→yes.  Auto tune enable. Range: 0→no; 1→yes.  Alarm power-up inhibit. Range: 0→no; 1→yes.  Key press remote action. Range: 0 to 9 1: tecla P 2: tecla ∧ 4: tecla ∨

0055	rSLL	D C
0033	r all	Remote Setpoint Low limit
		Range: Minimum value depends on the input type selected in <b>LYPE</b> , and maximum value is in <b>r5HL</b> .
0056	r5HL	Remote Setpoint High limit
		Range: Minimum value is in <b>r5LL</b> , and maximum depends on the input type selected in <b>LYPE</b> .
0057	10 1	
0058	10 2	Channel function I/O.
0059	lo 3	See Table 4.
0060	10 4	
0061 0062	lo 5	
0002	AILI	Alarm 1 Time 1. Range: 0 to 6500s Refer to operation manual for more details.
0063	A IFS	Alarm 1 Time 2 (in seconds)
		Range: same as in <b>A IL L</b>
0064	82£ 1	Alarm 2 Time 1 (in seconds)
		,
00/5		Range: same as in <b>A IL L</b>
0065	HSF5	Alarm 2 Time 2 (in seconds)
		Range: same as in <b>A IL L</b>
0066	SFSŁ	Soft-Start time (in seconds)
00/7		Range: 0 to 9999
0067	un IE	Temperature unit. Range: 0 to 1
		0→°C; 1→°F.
0068	ь IRS	Bias. Range: -100 to +100%.
0069	lo 5	•
0007		Channel function I/06. The available N2000 and N3000. See <b>Table 4</b> .
0070	R&S	
	Segment	Ramp and Soak segment being executed (read only). Range: 0 to 7
0071	Prn	Ramp and Soak segment to be viewed or edited.
		Range: 1 to 7
0072	Prn	Ramp and Soak segment to be executed
		Range: 0 to 7
0073	PE I	Segment 1 Event of R&S Program 1.
		Range: 0 to 15. See <b>Table 6</b> of the instructions.
0074	PE2	
0071	'	Segment 2 Event of R&S Program 1.
0075	653	Range: same as in <b>PE 1</b> .
0075	PE3	Segment 3 Event of R&S Program 1.
	<u>L_</u> _	Range: same as in <b>PE 1</b> .
0076	PEY	Segment 4 Event of R&S Program 1.
		Range: same as in <b>PE 1</b> .
0077	PE5	
		Segment 5 Event of R&S Program 1.
0070		Range: same as in <b>PE 1</b> .
0078	PE6	Segment 6 Event of R&S Program 1.
		Range: same as in <b>PE 1</b> .
0079	PE7	Segment 7 Event of R&S Program 1.
		Range: same as in <b>PE 1</b> .
0800	PE I	
	'.'	Segment 1 Event of R&S Program 2.
0001		Range: 0 to 15. See <b>Table 6</b> of the instructions.
0081	PE2	Segment 2 Event of R&S Program 2.
		Range: same as in <b>PE 1</b> .
0082	PE3	Segment 3 Event of R&S Program 2.
		Range: same as in <b>PE 1</b> .
0083	PE4	-
0003	""	Segment 4 Event of R&S Program 2.
		Range: same as in <b>PE 1</b> .
0084	PE5	Segment 5 Event of R&S Program 2.
		Range: same as in <b>PE I</b> .
		mange, same as my & 4.

0085	PE6	Command / Frank of DOC Drawson 2
0000	, 20	Segment 6 Event of R&S Program 2.  Range: same as in <b>PE 1</b> .
0086	PE7	Segment 7 Event of R&S Program 2. Range: same as in <b>PE 1</b> .
0087	PE I	Segment 1 Event of R&S Program 3. Range: 0 to 15. See <b>Table 6</b> of the instructions.
0088	PE2	Segment 2 Event of R&S Program 3. Range: same as in <b>PE 1</b> .
0089	PE3	Segment 3 Event of R&S Program 3. Range: same as in <b>PE 1</b> .
0090	PE4	Segment 4 Event of R&S Program 3. Range: same as in <b>PE 1</b> .
0091	PE5	Segment 5 Event of R&S Program 3. Range: same as in <b>PE 1</b> .
0092	PE6	Segment 6 Event of R&S Program 3. Range: same as in <b>PE 1</b> .
0093	PE7	Segment 7 Event of R&S Program 3. Range: same as in <b>PE 1</b> .
0094	PE I	Segment 1 Event of R&S Program 4. Range: 0 to 15. See <b>Table 6</b> of the instructions.
0095	PEZ	Segment 2 Event of R&S Program 4. Range: same as in <b>PE 1</b> .
0096	PE3	Segment 3 Event of R&S Program 4. Range: same as in <b>PE 1</b> .
0097	PE4	Segment 4 Event of R&S Program 4. Range: same as in <b>PE 1</b> .
0098	PE5	Segment 5 Event of R&S Program 4. Range: same as in <b>PE 1</b> .
0099	PE6	Segment 6 Event of R&S Program 4. Range: same as in <b>PE 1</b> .
0100	PET	Segment 7 Event of R&S Program 4. Range: same as in <b>PE 1</b> .
0101	PE I	Segment 1 Event of R&S Program 5. Range: 0 to 15. See <b>Table 6</b> of the instructions.
0102	PEZ	Segment 2 Event of R&S Program 5. Range: same as in <b>PE 1</b> .
0103	PE3	Segment 3 Event of R&S Program 5. Range: same as in <b>PE 1</b> .
0104	PE4	Segment 4 Event of R&S Program 5. Range: same as in <b>PE 1</b> .
0105	PES	Segment 5 Event of R&S Program 5. Range: same as in <b>PE 1</b> .
0106	PE6	Segment 6 Event of R&S Program 5. Range: same as in <b>PE 1</b> .
0107	PET	Segment 7 Event of R&S Program 5. Range: same as in <b>PE 1</b> .
0108	PE I	Segment 1 Event of R&S Program 6. Range: 0 to 15. See <b>Table 6</b> of the instructions.
0109	PE2	Segment 2 Event of R&S Program 6. Range: same as in <b>PE 1</b> .
0110	PE3	Segment 3 Event of R&S Program 6. Range: same as in <b>PE 1</b> .
0111	PE4	Segment 4 Event of R&S Program 6. Range: same as in <b>PE 1</b> .

0112	PE5	Segment 5 Event of R&S Program 6. Range: same as in <b>PE 1</b> .
0113	PE6	Segment 6 Event of R&S Program 6. Range: same as in <b>PE 1</b> .
0114	PE7	Segment 7 Event of R&S Program 6. Range: same as in <b>PE 1</b> .
0115	PE 1	Segment 1 Event of R&S Program 7. Range: 0 to 15. See <b>Table 6</b> of the instructions.
0116	PE2	Segment 2 Event of R&S Program 7. Range: same as in <b>PE 1</b> .
0117	PE3	Segment 3 Event of R&S Program 7. Range: same as in <b>PE 1</b> .
0118	PE4	Segment 4 Event of R&S Program 7. Range: same as in <b>PE 1</b> .
0119	PE5	Segment 5 Event of R&S Program 7. Range: same as in <b>PE 1</b> .
0120	PE6	Segment 6 Event of R&S Program 7. Range: same as in <b>PE 1</b> .
0121	PE7	Segment 7 Event of R&S Program 7. Range: same as in <b>PE 1</b> .
0122	PtoL	R&S Program 1 Tolerance (Ramp and Soak). Range: 0 to valor de ( <b>5PHL</b> - <b>5PLL</b> ).
0123	LP	Program 1 Link (Ramp and Soak). Range: 0 to 7
0124	PE I	Time 1 of Program 1. Range: 0 to 9999 minutes.
0125	PE2	Time 2 of Program 1. Range: 0 to 9999 minutes.
0126	PE3	Time 3 of Program 1. Range: 0 to 9999 minutes.
0127	PŁ4	Time 4 of Program 1. Range: 0 to 9999 minutes.
0128	PE5	Time 5 of Program 1. Range: 0 to 9999 minutes.
0129	PŁ6	Time 6 of Program 1. Range: 0 to 9999 minutes.
0130	PŁ7	Time 7 of Program 1. Range: 0 to 9999 minutes.
0131	PSP0	Setpoint 0 of Program 1. Range: From <b>5PLL</b> to <b>5PHL</b> .
0132	PSP I	Setpoint 1 of Program 1 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0133	PSP2	Setpoint 2 of Program 1 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0134	PSP3	Setpoint 3 of Program 1 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0135	P5P4	Setpoint 4 of Program 1 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0136	PSP5	Setpoint 5 of Program 1 (Ramp and Soak). Range: same as in <b>PSPO</b> .
0137	PSP6	Setpoint 6 of Program 1 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0138	PSP7	Setpoint 7 of Program 1 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0139	PtoL	R&S Program 2 Tolerance (Ramp and Soak). Range: 0 to valor de ( <b>SPHL - SPLL</b> ).
0140	LP	Program 2 Link (Ramp and Soak) Range: 0 to 7
0141	Pt 1	Time 1 of Program 2. Range: 0 to 9999 minutes.
0142	PŁ2	Time 2 of Program 2. Range: 0 to 9999 minutes.
0143	PŁ3	Time 3 of Program 2. Range: 0 to 9999 minutes.

0144	PŁ4	Time 4 of Program 2. Range: 0 to 9999 minutes.
0145	PŁS	Time 5 of Program 2. Range: 0 to 9999 minutes.
0146	PŁ6	Time 6 of Program 2. Range: 0 to 9999 minutes.
0147	PET	0 0
0148	PSP0	Time 7 of Program 2. Range: 0 to 9999 minutes.
0149	PSP 1	Setpoint 0 of Program 2. Range: From <b>SPLL</b> to <b>SPHL</b> .
	Fari	Setpoint 1 of Program 2 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0150	PSP2	Setpoint 2 of Program 2 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0151	PSP3	Setpoint 3 of Program 2 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0152	P5P4	Setpoint 4 of Program 2 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0153	PSP5	Setpoint 5 of Program 2 (Ramp and Soak). Range: same as in <b>P5PD</b> .
0154	PSP6	Setpoint 6 of Program 2 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0155	PSP7	Setpoint 7 of Program 2 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0156	PtoL	R&S Program 3 Tolerance (Ramp and Soak). Range: 0 to ( <b>SPHL - SPLL</b> ).
0157	LP	Program 3 Link (Ramp and Soak). Range: 0 to 7
0158	PE 1	Time 1 of Program 3. Range: 0 to 9999 minutes.
0159	PE2	Time 2 of Program 3 (Ramp and Soak). Range: same as in <b>PŁ 1</b> .
0160	Pt3	Time 3 of Program 3 (Ramp and Soak). Range: same as in <b>PŁ 1</b> .
0161	PE4	Time 4 of Program 3 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0162	PE5	Time 5 of Program 3 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0163	PŁ6	Time 6 of Program 3 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0164	PET	Time 7 of Program 3 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0165	PSP0	Setpoint 0 of Program 3. Range: from <b>5PLL</b> to <b>5PHL</b> .
0166	PSP I	Setpoint 1 of Program 3 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0167	PSP2	Setpoint 2 of Program 3 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0168	PSP3	Setpoint 3 of Program 3 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0169	PSP4	Setpoint 4 of Program 3 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0170	PSP5	Setpoint 5 of Program 3 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0171	PSP6	Setpoint 6 of Program 3 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0172	PSP7	Setpoint 7 of Program 3 (Ramp and Soak). Range: same as in <b>P5P0</b> .

0173	PtoL	R&S Program 4 Tolerance (Ramp and Soak). Range: 0 to ( <b>5PHL - 5PLL</b> ).
0174	LP	Program 4 Link (Ramp and Soak). Range: 0 to 7
0175	PŁ I	Time 1 of Program 4 (Ramp and Soak). Range: 0 to 9999 (in minutes)
0176	PE2	Time 2 of Program 4 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0177	PE3	Time 3 of Program 4 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0178	PE4	Time 4 of Program 4 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0179	PŁ5	Time 5 of Program 4 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0180	PŁ5	Time 6 of Program 4 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0181	PE7	Time 7 of Program 4 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0182	PSP0	Setpoint 0 of Program 4. Range: from <b>SPLL</b> to <b>SPHL</b> .
0183	PSP 1	Setpoint 1 of Program 4 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0184	PSP2	Setpoint 2 of Program 4 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0185	PSP3	Setpoint 3 of Program 4(Ramp and Soak). Range: same as in <b>PSP0</b> .
0186	PSP4	Setpoint 4 of Program 4 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0187	PSP5	Setpoint 5 of Program 4 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0188	PSP6	Setpoint 6 of Program 4 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0189	PSP7	Setpoint 7 of Program 4 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0190	PtoL	R&S Program 5 Tolerance (Ramp and Soak). Range: 0 to ( <b>5PHL</b> - <b>5PLL</b> ).
0191	LP	Program 5 Link (Ramp and Soak). Range: 0 to 7
0192	PE I	Time 1 of Program 5 (Ramp and Soak). Range: 0 to 9999. (in minutes)
0193	PE2	Time 2 of Program 5 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0194	PŁ3	Time 3 of Program 5 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0195	PŁ4	Time 4 of Program 5 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0196	PŁ5	Time 5 of Program 5 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0197	PŁ5	Time 6 of Program 5 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0198	PŁ7	Time 7 of Program 5 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0199	PSPO	Setpoint 0 of Program 5. Range: from <b>5PLL</b> to <b>5PHL</b> .

0200	PSP I	Setpoint 1 of Program 5 (Ramp and Soak). Range: same as in <b>P5PD</b> .
0201	PSP2	Setpoint 2 of Program 5 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0202	PSP3	Setpoint 3 of Program 5 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0203	PSP4	Setpoint 4 of Program 5 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0204	PSP5	Setpoint 5 of Program 5 (Ramp and Soak). Range: same as in <b>PSPO</b> .
0205	PSP6	Setpoint 6 of Program 5 (Ramp and Soak). Range: same as in <b>PSPO</b> .
0206	PSP7	Setpoint 7 of Program 5 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0207	PtoL	R&S Program 6 Tolerance (Ramp and Soak). Range: 0 to ( <b>SPHL</b> - <b>SPLL</b> ).
0208	LP	Program 6 Link (Ramp and Soak). Range: 0 to 7
0209	PE I	Time 1 of Program 6 (Ramp and Soak). Range: 0 to 9999. (in minutes)
0210	PŁ2	Time 2 of Program 6 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0211	P£3	Time 3 of Program 6 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0212	PE4	Time 4 of Program 6 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0213	PE5	Time 5 of Program 6 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0214	PŁ6	Time 6 of Program 6 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0215	PET	Time 7 of Program 6 (Ramp and Soak). Range: same as in <b>PL 1</b> .
0216	PSP0	Setpoint 0 of Program 6. Range: from <b>5PLL</b> to <b>5PHL</b> .
0217	PSP 1	Setpoint 1 of Program 6 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0218	PSP2	Setpoint 2 of Program 6 (Ramp and Soak). Range: same as in <b>PSPO</b> .
0219	PSP3	Setpoint 3 of Program 6 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0220	P5P4	Setpoint 4 of Program 6 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0221	PSP5	Setpoint 5 of Program 6 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0222	P5P6	Setpoint 6 of Program 6 (Ramp and Soak). Range: same as in <b>PSPD</b> .
0223	PSP1	Setpoint 7 of Program 6 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0224	PtoL	R&S Program 7 Tolerance (Ramp and Soak). Range: 0 to (SPHL - SPLL).
0225	LP	Program 7 Link (Ramp and Soak). Range: 0 to 7
0226	PE I	Time 1 of Program 7 (Ramp and Soak). Range: 0 to 9999. (in minutes)
0227	PE2	Time 2 of Program 7 (Ramp and Soak). Range: same as in <b>Pt 1</b> .

0228	PE3	Time 3 of Program 7 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0229	PŁY	Time 4 of Program 7 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0230	PŁ5	Time 5 of Program 7 (Ramp and Soak). Range: same as in <b>Pt. 1</b> .
0231	PŁ6	Time 6 of Program 7 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0232	PET	Time 7 of Program 7 (Ramp and Soak). Range: same as in <b>Pt 1</b> .
0233	PSP0	Setpoint 0 of Program 7. Range: from <b>SPLL</b> to <b>SPHL</b> .
0234	PSP I	Setpoint 1 of Program 7 (Ramp and Soak). Range: same as in <b>PSP0</b> .
0235	PSP2	Setpoint 2 of Program 7 (Ramp and Soak). Range: same as in <b>PSPO</b> .
0236	PSP3	Setpoint 3 of Program 7 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0237	PSP4	Setpoint 4 of Program 7 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0238	PSP5	Setpoint 5 of Program 7 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0239	PSP6	Setpoint 6 of Program 7 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0240	PSP1	Setpoint 7 of Program 7 (Ramp and Soak). Range: same as in <b>P5P0</b> .
0241	PrŁY	Parity of the serial communication.
0242	Prot	Sets up the Protection Level.
0243	Er.5P	Enables remote SP. 0 - Enables Remote SP 1 - Does not enable Remoto SP
0244	r.SP	Defines the signal type for the remote SP. 0: 0-20 mA 1: 4-20 mA 2: 0-5 V 3: 0-10 V
0245- 0253		Reserved.
0254	[]	Cold Juntion compensation temperature.
0255		Reserved.
0256	FL5h	Display flashes in alarm. Range: 0 a 15. See manual for details.
0257	R3L I	Time 1 temporization alarm 3. (in seconds).
0258	H3F5	Time 2 temporization alarm 3. (in seconds).
0259	RYE I	Time 1 temporization alarm 4. (in seconds).
0260	R4F5	Time 2 temporization alarm 4. (in seconds).
0261	Ł.SEG	Indicative screen. Shows the current segments remaining time.
0262		Reserved.
0263	E) L-	Reserved.
0264	FLEr	Digital filter for input signals. Range: 0 to 20.
0265- 0269		Reserved.
0270	1Eou	Percentage to be applied when the MV function safe output value is adopted.
0271	Lbd£	Time interval LBD function. Range: 0 to 9999. In minutes.

1.4 STATUS W	
Register	Value format
Status Word 1	bit 0 – Alarm 1 (0-inactive; 1-active)
	bit 1 – Alarm 2 (0-inactive; 1-active)
	bit 2 – Alarm 3 (0-inactive; 1-active)
	bit 3 – Alarm 4 (0-inactive; 1-active)
	bit 4 – Input – I/O 5 (0- inactive; 1- active)
	bit 5 – Input – I/O 3 (0- inactive; 1- active) (N1100)
	bit 6 – Input – I/O 4 (0- inactive; 1- active) (N1100)
	- Input – I/O 6 (0- inactive; 1- active) (N2000)
	bit 7 – Reserved
	bit 8 – Hardware type
	bit 9 – Hardware type
	bit 10 – Reserved
	bit 11 – Reserved
	bit 12 – Reserved
	bit 13 – Reserved
	bit 14 – Reserved
	bit 15 – Reserved
Status Word 2	bit 0 – Automatic (0- manual; 1- automatic)
	bit 1 – Run (0-stop; 1-run)
	bit 2 – Control Action (0- reverse; 1 - direct)
	bit 3 – Reserved
	bit 4 – Auto-tune (0-no; 1-yes)
	bit 5 – Alarm 1 power-up inhibit (0-no; 1-yes)
	bit 6 – Alarm 2 power-up inhibit (0-no; 1-yes)
	bit 7 – Alarm 3 power-up inhibit (0-no; 1-yes)
	bit 8 – Alarm 4 power-up inhibit (0-no; 1-yes)
	bit 9 – Unit (0-°C; 1-°F)
	bit 10 – Reserved
	bit 11 – Output 1 status
	bit 12 – Output 2 status
	bit 13 – Output 3 status
	bit 14 – Output 4 status
	bit 15 – Output 5 status
Status Word 3	bit 0 – Very low PV conversion (0-no; 1-yes)
	bit 1 – Negative conversion after calibration (0-no; 1-yes)
	bit 2 – Very high PV conversion (0-no; 1-yes)
	bit 3 – Exceeded linearization limit (0-no; 1-yes)
	bit 4 – Very high Pt100 cable resistance (0-no; 1-yes)
	bit 5 – Self zero conversion out of range (0-no; 1-yes)
	bit 6 – Self span conversion out of range (0-no; 1-yes)
	bit 7 – Cold junction conversion out of range (0-no; 1-yes)
	bit 8 – Reserved
	bit 9 – Reserved
	bit 10 – Reserved
	bit 11 – Reserved
	bit 12 – Reserved
	bit 13 – Reserved
	bit 14 – Reserved
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Table 2: Values of Status Words

bit 15 - Reserved

Writing to an output bit is only possible if the output has no function assigned to it (the output is configured to OFF in Alarm Cycle).

Coil Status	Output description
1	Output 1 Status (I/O1)
2	Output 2 Status (I/O2)
3	Output 3 Status (I/O3)
4	Output 4 Status (I/O4)
5	Output 5 Status (I/O5)

### 1.5 EXCEPTION RESPONSES - ERROR CONDITIONS

The MODBUS RTU protocol checks the CRC in the data blocks received.

Reception errors are detected by the CRC, causing the controller to discard the packet, not sending any reply to the master.

After receiving an error-free packet, the controller processes the packet and verifies whether the request is valid or not, sending back an exception error code in case of an invalid request. Response frames containing error codes have the most significant bit of the Modbus command set.

If a WRITE command sends an out-of-range value to a parameter, the controller will clamp the value to the parameter range limits, replying with a value that reflects these limits (maximum or minimum value allowed for the parameter).

The controller ignores broadcast READ commands; the controller processes only broadcast WRITE commands.

Error Code	Error Description		
01	Invalid Command		
02	Invalid Register Number or out of range		
03	Invalid Register Quantity or out of range		

Table 3 - Error Code

### 1.6 CONFIGURATION PARAMETERS I/O

I/O Function	Code		I/O Type
Digital Output to be set by the serial comm.	0	oFF	Digital Output
Alarm 1 Output	1	R I	Digital Output
Alarm 2 Output	2	A5	Digital Output
Alarm 3 Output	3	R3	Digital Output
Alarm 4 Output	4	ЯЧ	Digital Output
Time interval LBD function - Loop break detection	5	Lbd	Digital Output
PWM Control Output	6	ctrL	Digital Output
Automatic/Manual mode change	7	īΒn	Digital Input
Run/Stop mode change	8	LUN	Digital Input
Select Remote Set Point Input	9	r5P	Digital Input
Executes/Holds selected ramp and soak profile	10	HPrG	Digital Input
Enable/Disable R&S profile 1 selection	11	Pr 1	Digital Input
0 to 20mA Analog control output	12	C.D.20	Analog Output
4 to 20mA Analog control output	13	C.420	Analog Output
0 to 20mA PV retransmission	14	P.D.20	Analog Output
4 to 20mA PV retransmission	15	P.420	Analog Output
0 to 20mA SP retransmission	16	5.0.20	Analog Output
4 to 20mA SP retransmission	17	5.420	Analog Output

Table 4 – I/O functions Code