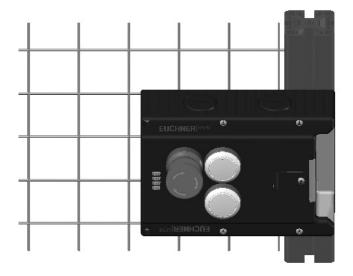
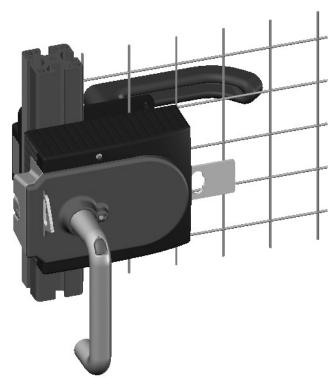


Operating Instructions





Safety Systems MGB-L1...-AR.-... / MGB-L2...-AR.-... MGB-L1...-AP.-... / MGB-L2...-AP.-... from V3.0.0

EN

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1. About this document

1.1. Scope

These operating instructions are valid for all MGB-L1...-AR.-... / MGB-L2...-AR.-... and MGB-L1...-AP.-... / MGB-L2...-AP.-... These operating instructions, the document *Safety information* and any enclosed data sheet form the complete user information for your device.

| Series | Guard locking types | System families | Product versions |
|--------|--|-----------------|------------------|
| | L1 (guard locking by spring force) | AP | from V3.0.0 |
| MGB | | AR | |
| MGB | 1.2 (ground leading by colonaid force) | AP | |
| | L2 (guard locking by solenoid force) | AR | |

1.1.1. Notes on older product versions

Products with lower product versions or without a version number are not described by these operating instructions. Please contact our support team in this case.

1.2. Target group

Design engineers and installation planners for safety devices on machines, as well as setup and servicing staff possessing special expertise in handling safety components.

1.3. Key to symbols

| Image: AP This section applies on operation as MGB-AP Image: AR This section applies on operation as MGB-AR Image: AR In this section attention must be paid to the DIP switch settings | Symbol/depiction | Meaning | |
|---|------------------|---|--|
| AR In this section attention must be paid to the DIP switch settings | | This section applies on operation as MGB-AP | |
| | AR | This section applies on operation as MGB-AR | |
| | | In this section attention must be paid to the DIP switch settings | |
| Printed document | | Printed document | |
| Www Document is available for download at www.euchner.com | www | Document is available for download at www.euchner.com | |
| DANGER Safety precautions DANGER Danger of death or severe injuries WARNING Caution Slight injuries possible | WARNING | Danger of death or severe injuries Warning about possible injuries | |
| Notice about possible device damage Important information | NOTICE | | |
| Tip Useful information | Tip | Useful information | |

 (\mathbf{i})

1.4. Supplementary documents

The overall documentation for this device consists of the following documents:

| Document title (document number) | Contents | |
|-------------------------------------|---|-----|
| Safety information (2525460) | Basic safety information | |
| Operating instructions (2119167) | (this document) | www |
| Possibly enclosed data sheet | Item-specific information about deviations or additions | |

Important!

Always read all documents to gain a complete overview of safe installation, setup and use of the device. The documents can be downloaded from www.euchner.com. For this purpose enter the doc. no. in the search box.

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2. Correct use

The system comprises at least one locking module MGB-L1-.../MGB-L2-... and one handle module MGB-H...

The safety system MGB is an interlocking device with guard locking (type 4). Devices with unicode evaluation possess a high coding level, devices with multicode evaluation possess a low coding level.

The locking module can be configured with the aid of DIP switches. Depending on the setting, the locking module behaves like an AP or AR device (see chapter 2.1. Main differences between MGB-AP and MGB-AR on page 7). In addition the guard lock monitoring can be switched on or off. More detailed information about the possible settings is available in the chapter 12.6. Changing device configuration (using DIP switches) on page 26.

With active guard lock monitoring, the following applies:

In combination with a movable guard and the machine control, this safety component prevents the guard from being opened while a dangerous machine function is being performed.

This means:

DIP

- Starting commands that cause a dangerous machine function must become active only when the guard is closed and locked.
- > The guard locking must not be released until the dangerous machine function has ended.
- Closing and locking a guard must not cause automatic starting of a dangerous machine function. A separate start command must be issued. For exceptions, refer to EN ISO 12100 or relevant C-standards.

With inactive guard lock monitoring, the following applies:

In combination with a movable guard and the machine control, this safety component prevents dangerous machine functions from occurring while the guard is open. A stop command is triggered if the guard is opened during the dangerous machine function. With inactive guard lock monitoring, guard locking must be used only for process protection.

This means:

- Starting commands that cause a dangerous machine function must become active only when the guard is closed.
- Opening the guard triggers a stop command.
- Closing a guard must not cause automatic starting of a dangerous machine function. A separate start command must be issued. For exceptions, refer to EN ISO 12100 or relevant C-standards.

Before the device is used, a risk assessment must be performed on the machine, e.g. in accordance with the following standards:

- EN ISO 13849-1
- EN ISO 12100
- IEC 62061

Correct use includes observing the relevant requirements for installation and operation, particularly based on the following standards:

- EN ISO 13849-1
- EN ISO 14119
- EN 60204-1

The safety system MGB can be combined only with the intended modules in the MGB system family.

On the modification of system components, EUCHNER provides no warranty for function.



| Locking modules with the configuration MGB-AR can be integrated into an AR switch chain.

Connection of several devices in an AR switch chain is permitted only using devices intended for series connection in an AR switch chain. Check the operating instructions for the related device.



| i | Important! |
|---|--|
| | The user is responsible for the proper integration of the device into a safe overall system. For this purpose, the overall system must be validated, e.g. in accordance with EN ISO 13849-2. Correct use requires observing the permissible operating parameters (see chapter 14. Technical data on page 36). If a data sheet is included with the product, the information on the data sheet applies. |

Table 1: Possible combinations for MGB components

| Evaluation unit | MGB-H from V2.0.0 |
|-------------------------|----------------------|
| MGBAR/AP from V3.0.0 | • |
| Key to symbols | Combination possible |

2.1. Main differences between MGB-AP and MGB-AR

| System family | Symbol | Use |
|---------------|--------|--|
| MGB-AP | AP | Optimized for operation in safe control systems. If series connection is not necessary, the number of terminals required can be reduced using this system family. |
| MGB-AR | AR | Linking of several guards on one shutdown path. As a consequence several safety doors can be very simply polled using one evalua- tion unit or two control system inputs. |

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3. Description of the safety function

Devices from this series feature the following safety functions:

With active guard lock monitoring, the following applies:



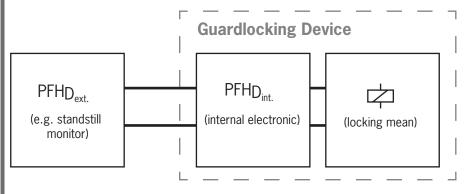
- Monitoring of guard locking and the position of the guard (interlocking device with guard locking according to EN ISO 14119)
- Safety function (see chapter 6. Function on page 10):
- The safety outputs are switched off when guard locking is released (monitoring of the locking element). **Important:** This applies only if guard lock monitoring is active!
- The safety outputs are switched off when the guard is open.
- Guard locking can be activated only when the bolt tongue is located in the locking module (prevention of inadvertent locking position (faulty closure protection)).
- Safety characteristics: category, Performance Level, PFH_D (see chapter 14. Technical data on page 36).

Control of guard locking

Safety function

If the device is used as guard locking for personnel protection, control of guard locking must be regarded as a safety function.

The safety level of guard locking control is determined by the device $PFH_{D_{int.}}$ and by the external control (e.g. $PFH_{D_{ext.}}$ of the standstill monitor).



Safety characteristics: category, Performance Level, PFH_D (see chapter 14. Technical data on page 36).

With inactive guard lock monitoring, the following applies:



Monitoring of the guard position (interlocking device according to EN ISO 14119)

- Safety function: The safety outputs are switched off when the guard is open (see chapter 6. Function on page 10).
- Safety characteristics: category, Performance Level, PFH_D (see chapter 14. Technical data on page 36).

The following applies to devices with emergency stop:

Emergency stop (emergency stop device according to EN ISO 13850)

- Safety function: emergency stop function
- » Safety characteristics: B_{10D} value (see chapter 14. Technical data on page 36)

4. Exclusion of liability and warranty

In case of failure to comply with the conditions for correct use stated above, or if the safety regulations are not followed, or if any servicing is not performed as required, liability will be excluded and the warranty void.

5. General safety precautions

Safety switches fulfill personnel protection functions. Incorrect installation or tampering can lead to fatal injuries to personnel.

Check the safe function of the safeguard particularly

- after any setup work
- ▶ after the replacement of an MGB component
- after an extended period without use
- after every fault
- after any change to the DIP switch settings

Independent of these checks, the safe function of the safeguard should be checked at suitable intervals as part of the maintenance schedule.

| | WARNING |
|--|---|
| | Danger to life due to improper installation or due to bypassing (tampering). Safety components fulfill a personnel protection function. |
| | Safety components must not be bypassed, turned away, removed or otherwise rendered ineffec- tive. On this topic pay attention in particular to the measures for reducing the possibility of bypass- ing according to EN ISO 14119:2013, section 7. |
| The switching operation is allowed to be triggered only by the intended handle module MC that is positively fastened to the guard. | |
| | Prevent bypassing by means of replacement actuators (only for multicode evaluation). For this purpose, restrict access to actuators and to keys for releases, for example. |
| | Mounting, electrical connection and setup only by authorized personnel possessing the following knowledge: specialist knowledge in handling safety components knowledge about the applicable EMC regulations |
| | - knowledge about the applicable regulations on operational safety and accident prevention. |
| | Important! |
| (i) | |
| | Prior to use, read the operating instructions and keep these in a safe place. Ensure the operating instructions are always available during mounting, setup and servicing. EUCHNER cannot provide any warranty in relation to the readability of the CD for the storage period required. For this reason you should archive a printed copy of the operating instructions. You can download the operating instructions from www.euchner.com. |

6. Function

Together with a handle module, the locking module makes it possible to lock movable guards. The combination also serves as a mechanical door stop at the same time.



The following switch-on condition applies to the safety outputs FO1A and FO1B (also see chapters 15.2. System status table MGB-AP on page 40):

| | Configuration | System family | | MGB-AR | | MGB-AP | |
|-----------|--|-----------------------|--------------|--------------|-------------------|----------|--|
| | | Guard lock monitoring | Active | Inactive | Active | Inactive | |
| | No fault in the device | | TRUE | TRUE | TRUE | TRUE | |
| | Guard closed | | TRUE | TRUE | TRUE | TRUE | |
| Ę | Bolt tongue inserted in locking mo | dule | TRUE | TRUE | TRUE | TRUE | |
| Condition | Guard locking active | TRUE | Not relevant | TRUE | Not relevant | | |
| Con | In case of series connection: Signal available from the upstream FI1B In case of separate operation: DC 24 V present at the safety input | TRUE | TRUE | Not relevant | Not relevant | | |
| | | | | F01A and F | 01B are ON | | |

The locking module detects the position of the guard and the position of the bolt tongue. The position of the guard locking is also monitored.

Guard lock monitoring can be deactivated using DIP switches (see chapter 12.6. Changing device configuration (using DIP switches) on page 26).



Important!

For use as guard locking for personnel protection in accordance with EN ISO 14119, guard lock monitoring must be active.

The bolt tongue in the handle module is moved into and out of the locking module by actuating the door handle.

When the bolt tongue is fully inserted into the locking module, the locking arm locks the bolt tongue in this position. Depending on version, this locking is by spring force or solenoid force.

6.1. Guard locking for version MGB-L1

(guard locking actuated by spring force and released by power-ON)

Activating guard locking: close guard; no voltage at the solenoid.

Releasing guard locking: apply voltage to the solenoid.

The spring-operated guard locking functions in accordance with the closed-circuit current principle. If the voltage is interrupted at the solenoid, the guard locking remains active and the guard cannot be opened directly.



Important!

If the guard is open when the power supply is interrupted and is then closed, guard locking is activated. This can lead to persons being locked in unintentionally.

As long as the locking arm is closed, the bolt tongue cannot be pulled out of the locking module and the guard is locked. When voltage is applied to the guard locking solenoid, the locking arm is opened and bolt tongue is released. The guard can be opened. G

6.2. Guard locking for version MGB-L2

(guard locking actuated by power-ON and released by spring force)

Important!

Use as guard locking for personnel protection is possible only in special cases, after strict assessment of the accident risk (see EN ISO 14119:2013, section 5.7.1)!

Activating guard locking: apply voltage to the solenoid.

Releasing guard locking: disconnect voltage from the solenoid.

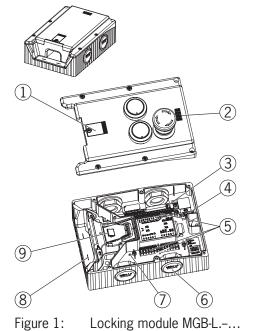
The magnetically actuated guard locking operates in accordance with the open-circuit current principle. If the voltage is interrupted at the solenoid, the guard locking is released and the guard can be opened directly!

The guard can be opened as long as no voltage is applied to the guard locking solenoid.

When voltage is applied to the guard locking solenoid, the locking arm is held in the locked position and the guard is locked.

7. System overview

7.1. Locking module MGB-L.-...



7.2. Handle module MGB-H-...

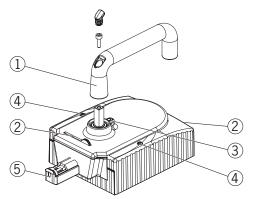


Figure 2: Handle module MGB-H-...

7.3. Escape release MGB-E-... (optional)

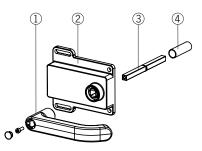


Figure 3: Escape release MGB-E-...

| Cover for | auxiliary release |
|-----------|-------------------|
| LED india | ator |

- LED indicator
- Jumper
- DIP switches
- Terminals X2-X5
 - Depending on version:
 - cable entry M20x1.5 or plug connector
- Internal reset
- Auxiliary marking for maximum permitted mounting distance
- Locking arm

Notice:

Key: 1 2

3 4

5

6

(7)

(8)

9

Depending on version, additional controls and indicators may be integrated into the cover and a mounting plate can be included. See enclosed data sheet.

Key:

- ① Door handle
- Fold-out lockout mechanism (2)
- (optional: second, automatically extending lockout mechanism) Locking pin for handle adjustment 3
- Locking screws T10 for housing cover (4)
- (5) Bolt tongue

Notice:

Key:

2

(3)

(4) Notice:

① Door handle Housing

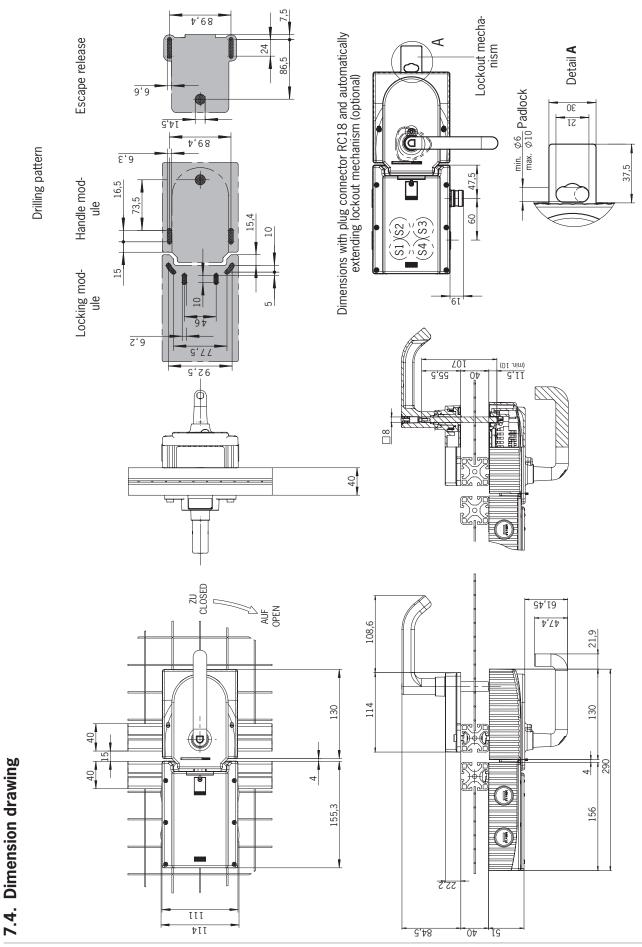
Actuation axis 8 x 8 mm

See enclosed data sheet.

(different lengths available) Protective sleeve

Depending on version, a mounting plate can be included. See enclosed data sheet.

Depending on version, a mounting plate can be included.



Dimension drawing MGB fitted, without optional mounting plates

EN

Figure 4:

8. Manual release

Some situations require the guard locking to be released manually (e.g. malfunctions or an emergency). A function test should be performed after release.

More information on this topic can be found in the standard EN ISO 14119:2013, section 5.7.5.1. The device can feature the following release functions:

8.1. Auxiliary release

In the event of service, the guard locking can be released with the auxiliary release irrespective of the state of the solenoid (see *Figure 5*).



• When release monitoring is active, the system enters into a latching fault when the auxiliary release is actuated. See *System status table, signal sequence incorrect* status (DIA red, Lock flashes 1 time).

• The system might not enter into a latching fault if the auxiliary release is actuated very slowly.

| $\overline{(\mathbf{i})}$ | Important! |
|---------------------------|--|
| Ŭ | The auxiliary release must be reset at the control system level, e.g. by means of a plausibili- ty check (status of the safety outputs does not match the guard locking control signal). See EN ISO 14119:2013, sec. 5.7.5.4. |
| | The auxiliary release is not a safety function. |
| | The machine manufacturer must select and use a suitable release (escape release, emergency release, etc.) for a specific application. A hazard assessment is required for this purpose. It may be necessary to take specifications from a product standard into account. |
| | The correct function must be checked at regular intervals. |
| | Loss of the release function due to mounting errors or damage during mounting. Check the re- lease function every time after mounting. |
| | Please observe the notes on any enclosed data sheets. |

The locking screw must be screwed back in and sealed (for example with sealing lacquer) after assembly and after every use of the auxiliary release. Tightening torque 0.5 Nm.

- 1. Undo locking screw.
- 2. Lift locking arm using a screwdriver and actuate door handle.

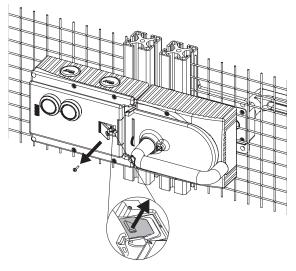


Figure 5: Auxiliary release

ĺÌ

8.2. Emergency release (can be retrofitted)

Permits opening of a locked guard from outside the danger zone without tools. For mounting, see the mounting supplement.

Important!

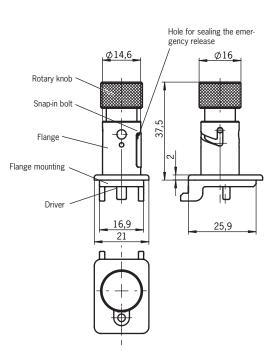
- It must be possible to operate the emergency release manually from outside the protected area without tools.
- The emergency release must possess a marking indicating that it may be used only in an emergency.
- The actuator must not be under tensile stress during manual release.
- The release function meets all other requirements from EN ISO 14119.
- The emergency release meets the requirements of Category B according to EN ISO 13849-1:2008.
- > Loss of the release function due to mounting errors or damage during mounting.
- Check the release function every time after mounting.
- > Please observe the notes on any enclosed data sheets.

8.2.1. Actuating emergency release

- Press emergency release and turn clockwise by 90° until it clicks into place.
- ➡ Guard locking is released.

To reset, press the snap-in bolt inward using a small screwdriver or similar tool and turn the emergency release back. The emergency release must be sealed in the free position.

The safety outputs \mathbf{P} are switched off when the emergency release is actuated. Use the safety outputs \mathbf{P} to generate a stop command.



8.3. Lockout mechanism

If the lockout mechanism is pivoted out/extended, the bolt tongue cannot be extended. The lockout mechanism can be secured with padlocks (see *Figure 6*).

✤ To pivot out, press the grooved part (possible only with bolt tongue retracted).

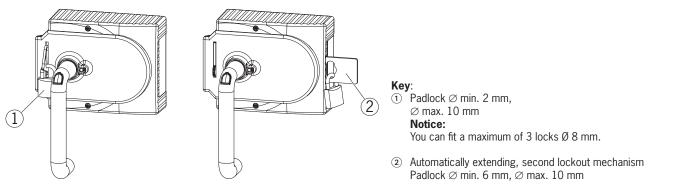


Figure 6: Lockout mechanism secured with padlock

ΕN

8.4. Escape release (optional)

The escape release is used to open a locked guard from the inside without tools.



 (\mathbf{i})

When release monitoring is active, the system enters into a latching fault when the escape release is actuated. See *System status table, signal sequence incorrect* status (DIA red, Lock flashes 1 time). The system might not enter into a latching fault if the escape release is actuated very slowly.

Important!

- It must be possible to actuate the escape release manually from inside the protected area without tools.
- + It must not be possible to reach the escape release from the outside.
- The actuator must not be under tensile stress during manual release.
- The escape release meets the requirements of Category B according to EN ISO 13849-1:2008.
- Fit escape release such that operation, inspection and maintenance are possible.
- The actuation axis for the escape release must be inserted min. 10 mm into the handle module. Note the information on the different profile widths in the next chapter.
- Adjust escape release axis at right angles to the handle module. See Figure 4 and Figure 8.

8.4.1. Preparing escape release

(also see Figure 7: Preparing escape release on page 17)

| Profile width | Length required for actuation axis | | Which EUCHNER parts are required? | Necessary work steps |
|---------------|------------------------------------|--|--|--|
| | Without plates | With mounting plates (4 mm each) | | |
| D | D+13 | D+21 | | |
| 30 mm | 43 mm | 51 mm | Standard escape release with 110 mm axis (order no. 100465) | Shorten to required length |
| 40 mm | 53 mm | 61 mm | Standard escape release with 110 mm axis (order no. 100465) If necessary, extended actuation axis (order no. 106761) | Without mounting plates: none With mounting plates: Use extended actuation axis and protective sleeve and shorten to required length |
| 45 mm | 58 mm | 66 mm | Standard escape release with 110 mm axis (order no. 100465) and extended actuation axis (order no. 106761) | Use long actuation axis and protective sleeve and short- en to required length |
| 50 mm | 63 mm | 71 mm | Standard escape release with 110 mm axis (order no. 100465) and extended actuation axis (order no. 106761) | Use long actuation axis and protective sleeve and short- en to required length |

Actuation axis Protective sleeve <u>M</u>4 (+4 mm per mounting plate) (+4 mm per mounting plate) 55,5 55,5 82 D-1 Escape release 250 D + 10,25 ±1,25 2 2 Handle module (11, (A)1 0 (4) B 3**0**

- ① Insert actuation axis. The snap ring **A** must be in contact with the escape release **B**.
- 2 Fit door handle.3 Tighten fixing sci
- $\overline{3}$ Tighten fixing screw to 2 Nm and push in cap.
- ④ Fit protective sleeve.

Figure 7: Preparing escape release

Example without mounting plates:

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9. Mounting



WARNING

Mounting must be performed only by authorized personnel.

With two-leaf hinged doors, one of the two door leaves must also be latched mechanically.

Use a rod latch (Item) or a double-door lock (Bosch Rexroth) for this purpose, for example.

| (i) | Important!If installed flush, the switching distance changes as a function of the installation depth and the guard material. |
|--------------|---|
| | Actuating range |
| | Locking module Handle module |
| | Flush installation |
| | |
| | |
| | Actuating range |
| | Locking module Handle module |
| | Surface mounting |

| i | Tip! |
|------------|---|
| \bigcirc | You will find an animation on the mounting process at www.euchner.com. The color and labeling of pushbuttons and indicators can be modified. |

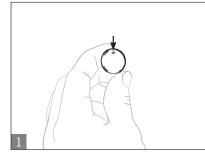
For mounting steps, see Figure 8 and Figure 9 to Figure 14.

Attach system such that operation of the auxiliary release as well as inspection and maintenance are possible.

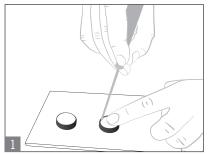
The locking screw of the auxiliary release must be returned to its original position and sealed before putting into operation (for example with sealing lacquer).

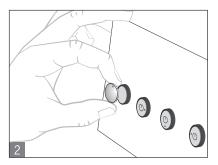
9.1. Mounting lens

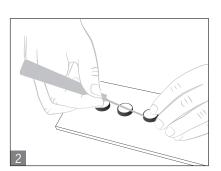
Mounting

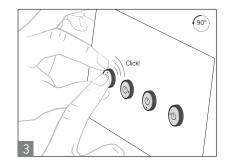


Removal











EN



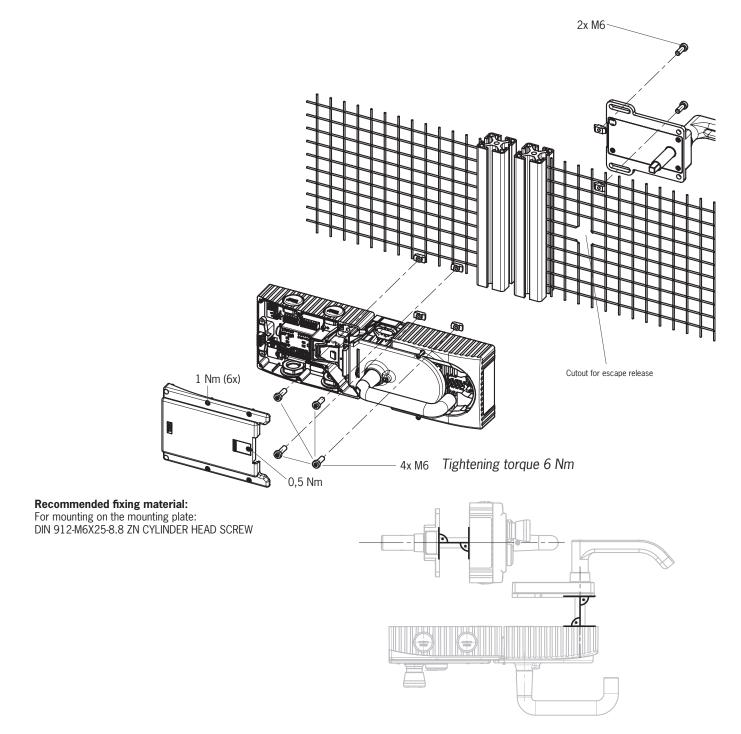


Figure 8: Installation example for door hinged on the right (general view)

10. Changing actuating direction (here: from right to left)

(\mathbf{i})

It is possible to make this change only when the bolt tongue is not extended and an escape release is not yet mounted.

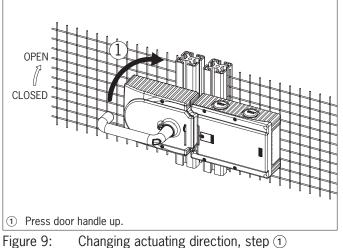
As supplied, the handle module is set either for doors hinged on the right or for doors hinged on the left.

Based on the example of a handle module for doors hinged on the right this means:

• The guard opens by pressing down the door handle.

Important!

• The system is mounted the other way around for doors hinged on the left. In other words, the guard opens by pressing up the door handle (see *Figure 9*). For this reason the actuating direction of the door handle must be changed (see *Figure 9* to *Figure 14*).



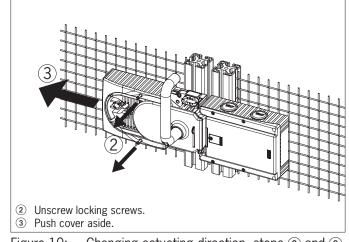
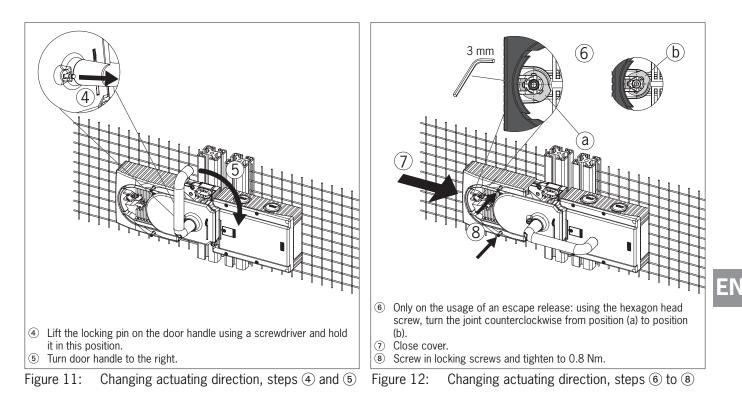
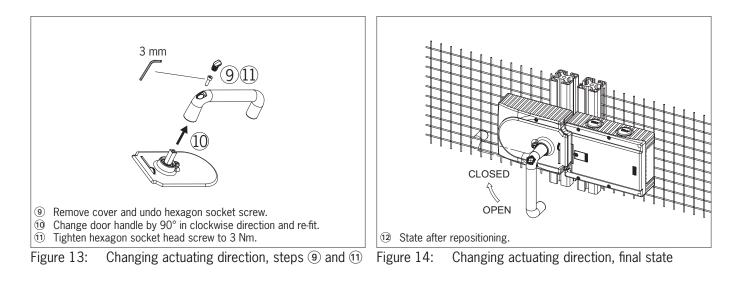


Figure 10: Changing actuating direction, steps (2) and (3)



(Similarly on handle modules for doors hinged on the left)



11. Protection against environmental effects

Lasting and correct safety function requires that the system must be protected against foreign bodies such as swarf, sand, blasting shot, etc., which can become lodged in the locking and handle modules. For this purpose a suitable installation position should be selected.

Cover device during painting work!

12. Electrical connection



WARNING

In the event of a fault, loss of the safety function due to incorrect connection.

- To ensure safety, both safety outputs (FO1A and FO1B) must always be evaluated.
- > The monitoring outputs must not be used as safety outputs.
- > Lay the connecting cables with protection to prevent the risk of short circuits.

| A | CAUTION |
|----------|--|
| | CAUTION |
| | Risk of damage to equipment or malfunctions as a result of incorrect connection. |
| | The inputs on a connected evaluation unit must be positive switching, as the two outputs on the safety switch deliver a level of +24 V in the switched-on state. |
| | All the electrical connections must either be isolated from the mains supply by a safety transform- er according to EN IEC 61558-2-6 with limited output voltage in the event of a fault, or by other equivalent insulation measures. |
| | All electrical outputs must have an adequate protective circuit for inductive loads. The outputs must be protected with a free-wheeling diode for this purpose. RC interference suppression units must not be used. |
| | Power devices which are a powerful source of interference must be installed in a separate location away from the input and output circuits for signal processing. The cable routing for safety circuits should be as far away as possible from the cables of the power circuits. |
| | To prevent EMC problems, it is imperative you follow the chapter 12.5. Notes on cable laying on page 25. Follow EMC notes on devices in the immediate vicinity of the MGB system and their cables. |
| | In order to avoid EMC interference, the physical environmental and operating conditions at the installation site of the device must comply with the requirements according to the standard DIN EN 60204-1:2006, section 4.4.2/EMC. |
| | |
| i | Important! |
| - | If the device does not appear to function when the operating voltage is applied (e.g. green Power LED does not illuminate), the safety switch must be returned to the manufacturer. |
| | To ensure the stated degree of protection is achieved, the cover screws must be tightened to a tightening torque of 1 Nm. |
| | Tighten screw for the cover for the auxiliary release to 0.5 Nm. |

12.1. Notes about 🖓 🗤

 \mathbf{i}

Important!

- This device is intended to be used with a Class 2 power source in accordance with UL1310¹). As an alternative a LV/C (Limited Voltage/Current) power source with the following properties can be used:
- This device shall be used with a suitable isolating source in conjunction with a fuse in accordance with UL 248. The fuse shall be rated max. 3.3 A and be installed in the max. 30 V/DC power supply to the device in order to limit the available current to comply with the ${}^{\textcircled{m}}$ requirements. Please note possibly lower connection ratings for your device (refer to the technical data).

1) Notice on the scope of the UL approval: only for applications as per NFPA 79 (Industrial Machinery). The devices are tested in accordance with UL 508 (protection against electric shock and fire).

12.2. Safety in case of faults

- The operating voltage UB is reverse polarity protected.
- > The safety outputs F01A/F01B are short circuit-proof.
- A short circuit between FI1A and FI1B or FO1A and FO1B is detected by the device.
- A short circuit in the cable can be excluded by laying the cable with protection.

12.3. Fuse protection for power supply

The power supply must be provided with fuse protection depending on the number of devices and the current required for the outputs. The following rules apply:

Max. current consumption of an individual device ${\sf I}_{\rm max}$

- $I_{max} = I_{UB} + I_{UA} + I_{FO1A+FO1B}$
- I_{UB} = Device operating current (80 mA)
- I_{UA} = Load current of monitoring outputs OD, OT, OL and OI (4 x max. 50 mA) + solenoid + control elements

 $I_{FO1A+FO1B}$ = Load current of safety outputs FO1A + FO1B (2 x max. 200 mA)

Max. current consumption of a switch chain ΣI_{max}

 $\Sigma I_{max} = I_{FO1A+FO1B} + n x (I_{UB} + I_{UA})$

n = Number of connected devices

Assignment of the currents to the fuse circuits

| Current | Fuse circuit F1 | Fuse circuit F2 |
|------------------------|-------------------|--|
| I _{UB} | 80 mA | |
| I _{F01A+F01B} | (2 x max. 200 mA) | |
| | | I _{solenoid} = 375 mA |
| | | $I_{OD,OT,OL,OI} = (4 \text{ x max. 50 mA})$ |
| I | | I _{control elements} = max. 100 mA |
| lua | | (per control element) |
| | | l _{indicators} = max. 5 mA |
| | | (per indicator) |

12.4. Requirements for connecting cables

CAUTION

\triangle

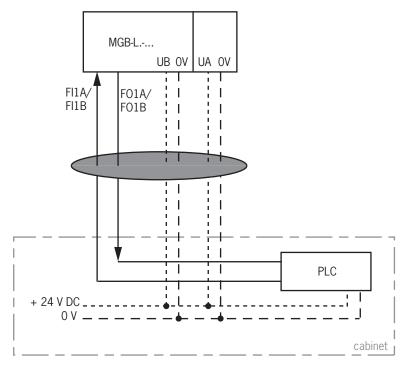
Risk of damage to equipment or malfunctions as a result of incorrect connecting cables.
On the use of other connection components, the requirements in the following table apply.
EUCHNER provides no warranty for safe function in case of failure to comply with these requirements.

Observe the following requirements with respect to the connecting cables:

| Parameter | Value | Unit |
|-------------------------------|-------|-----------------|
| Conductor cross-section, min. | 0.13 | mm ² |
| R max. | 60 | Ω/km |
| C max. | 120 | nF/km |
| L max. | 0.65 | mH/km |

12.5. Notes on cable laying

Lay all MGB connection cables in a common cable harness.



Important: lay cables in a common harness

Figure 15: Stipulated cable laying

EUCHNER

12.6. Changing device configuration (using DIP switches)

(\mathbf{i})

You will find an animation on device configuration at www.euchner.com.

DIP switches

The device can be configured using the DIP switches. The following settings are possible:

Changing system family (AR/AP switching)

Tip!

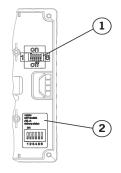
- Deactivating guard lock monitoring
- > Activating release monitoring (possible only with active guard lock monitoring)

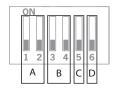
Position of the switches

| ltem | Description | |
|------|------------------------------|--|
| 1 | DIP switch | |
| 2 | Sticker with factory setting | |

Function of the switches

| Detail | Switch | Function | |
|--------|--|---|--|
| A | 1+2 on: device is operated as an AP system | | |
| | | off: device is operated as an AR system | |
| В | 3+4 on: guard lock monitoring is deactivated | | |
| | | off: guard lock monitoring is active (usually factory setting) | |
| С | 5 | on: configuration possible | |
| | | off: configuration inhibited (factory setting) | |
| D | 6 | on: release monitoring is activated | |
| | | off : release monitoring is deactivated (usually factory setting) | |



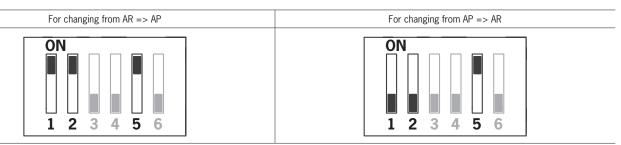


12.6.1. Changing system family (AR/AP switching)

CAUTION

Malfunction due to incorrect configuration or incorrect connection.
Note that the terminal assignment also changes on changing the configuration (see chapter 12.9. Terminal assignment and contact description on page 30).

- 1. Switch off power supply.
- 2. Set DIP switches 1, 2 and 5 as shown.



- 3. Switch on power supply for 5 s.
- ➡ The change is confirmed by the illumination of the Power LED. All other LEDs are off.
- 4. Switch off power supply and set DIP switch 5 to OFF.
- ➡ The next time the device is started, it operates in the operating mode set.

12.6.2. Deactivating guard lock monitoring

WARNING



Risk of injury due to inactive guard lock monitoring.

With inactive guard lock monitoring, the guard locking position does not influence the safety outputs. The guard can be opened immediately. This setting is not allowed to be used in applications in which, e.g., there is a hazard due to overrunning machinery movement. With inactive guard lock monitoring, guard locking must be used only for process protection.

- 1. Switch off power supply.
- 2. Set DIP switches 3-5 as shown.



- 3. Switch on power supply for 5 s.
- ➡ The change is confirmed by the illumination of the Power LED. All other LEDs are off.
- 4. Switch off power supply and set DIP switch 5 to OFF.
- The next time the device is started, it operates in the operating mode set.

12.6.3. Activating release monitoring

| (\mathbf{i}) | Important! |
|----------------|---|
| | Release monitoring can be activated only if guard lock monitoring is also active. |

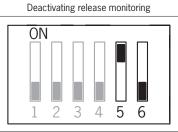
(\mathbf{i})

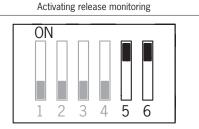
NOTICE

When release monitoring is active, the system enters into a latching fault when the escape release or auxiliary release is actuated.

See System status table, signal sequence incorrect status (DIA red, Lock flashes 1 time).

- 1. Switch off power supply.
- 2. Set DIP switches 5 and 6 as shown.





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- 3. Switch on power supply for 5 s.
- ➡ The change is confirmed by the illumination of the Power LED. All other LEDs are off.
- 4. Switch off power supply and set DIP switch 5 to OFF.
- The next time the device is started, it operates in the operating mode set.

12.7. Notes on operation with control systems

Please observe the following requirements for connection to safe control systems:

General notes

- > Use a common power supply for the control system and the connected safety switches.
- A pulsed power supply must not be used for UB/UA. Tap the supply voltage directly from the power supply unit. If the power supply is connected to a terminal of a safe control system, this output must provide sufficient electrical current.
- The safety outputs (FO1A and FO1B) can be connected to the safe inputs of a control system. Prerequisite: the input must be suitable for pulsed safety signals (OSSD signals, e.g. from light grids). The control system must tolerate test pulses on the input signals. This normally can be set up by parameter assignment in the control system. Observe the notes of the control system manufacturer. For the pulse duration of your safety switch, please refer to chapter 14. Technical data on page 36.
- The inputs on a connected evaluation unit must be positive switching, as the two outputs on the safety switch deliver a level of +24 V in the switched-on state.



 Always connect inputs FI1A and FI1B directly to a power supply unit or to outputs FO1A and FO1B of another EUCHNER AR device (series connection). Pulsed signals must not be present at inputs FI1A and FI1B. The test pulses are also present when the safety outputs are switched off (only on FO1A). Depending on the inertia of the downstream device (control system, relay, etc.), this can lead to short switching processes.

Guard locking control

• Test pulses up to max. 5 ms in duration at intervals of min. 100 ms are tolerated on IMP1, IMP2 and IMM.

| (\mathbf{i}) | NOTICE | | |
|----------------|---|--|--|
| | Due to the fact that short circuit monitoring of the safety outputs FO1A/FO1B is performed by the device itself, the Performance Level in accordance with EN 13849 is not reduced if the control system pulsing is switched off. | | |
| | Tip! | | |
| (\mathbf{i}) | TIP: | | |
| \bigcirc | A detailed example of connecting and setting the parameters of the control system is available for many devices at www.euchner.com, in the area <i>Service/Downloads/Applications</i> . The features of the respective device are dealt with there in greater detail. | | |

12.8. Connection of guard locking control

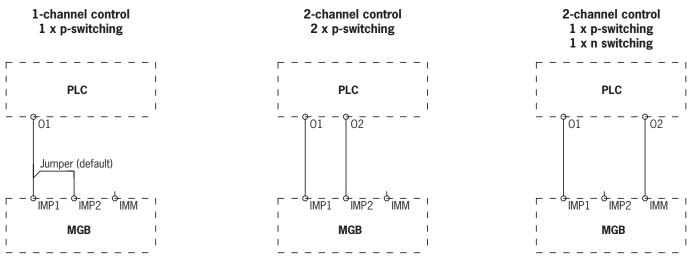
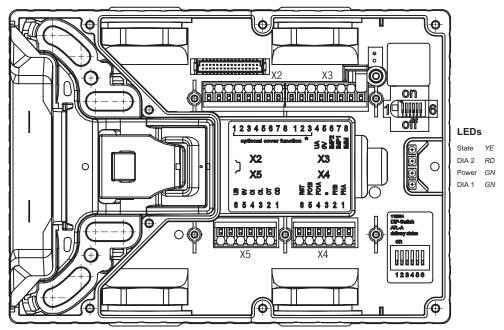


Figure 16: Connection options for guard locking control

With 2-channel control, the jumper between IMP1 and IMP2 must be removed. Connection as shown above. Further adaptations may be required for some device versions with plug connector M23 (RC18) (see data sheet).

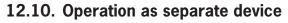


12.9. Terminal assignment and contact description

Figure 17: Connections and LEDs

| Terminal | Designation | Description | | |
|--------------|-------------|--|--|--|
| X3.1 to X3.3 | - | See the enclosed data sheet | | |
| X3.4 | UA | Power supply for the guard locking solenoid, monitoring outputs and cover assembly, DC 24 V, must be present continuously so that the guard locking solenoid functions. | | |
| X3.5 | OV | Ground, DC 0 V (connected internally to X5.5). | | |
| X3.6 | IMP2 | Control voltage for switching the guard locking on and off, DC 24 V (see chapter 12.8. Connection of guard locking control on page 29). | | |
| X3.7 | IMP1 | Control voltage for switching the guard locking on and off, DC 24 V (see chapter 12.8. Connection of guard locking control on page 29). | setting on delivery | |
| X3.8 | IMM | Control voltage for switching the guard locking on and off, 0 V (see chapter | 12.8. Connection of guard locking control on page 29). | |
| X4.1 | FI1A | With AR configuration: enable input for channel A, connect to DC 24 V in separate operation. In case of switch chains, connect output signal FO1A from previous device. With AP configuration: input is not evaluated. | | |
| X4.2 | FI1B | With AR configuration: enable input for channel B, connect to DC 24 V in separate operation. In case of switch chains, connect output signal F01B from previous device. With AP configuration: input is not evaluated. | | |
| X4.3 | - | See the enclosed data sheet | | |
| X4.4 | F01A | Safety output channel A (function dependent on DIP switch setting) Guard lock monitoring active: ON when door is closed and locked . Guard lock monitoring inactive: ON when door is closed and bolt tongue is inserted. | | |
| X4.5 | F01B | Safety output channel B (function dependent on DIP switch setting) Guard lock monitoring active: ON when door is closed and locked Guard lock monitoring inactive: ON when door is closed and bolt tongue is inserted. | | |
| X4.6 | RST | Reset input, device is reset if DC 24 V is applied to RST for at least 3 s. | | |
| X5.1 | OD | Door monitoring output, ON when the door is closed. | | |
| X5.2 | OT | Bolt tongue monitoring output, ON when the door is closed and the bolt tongue is inserted into the locking module. | | |
| X5.3 | OL | Guard lock monitoring output, ON when the door is closed and locked. | | |
| X5.4 | OI | Diagnostics monitoring output, ON when the device is in the fault state. | | |
| X5.5 | OV | Ground, DC 0 V (connected internally to X3.5). | | |
| X5.6 | UB | Power supply, DC 24 V | | |
| X2.1 to X2.8 | - | See the enclosed data sheet | | |
| X1 | - | Reserved for connection of the cover circuit board (only for populated covers) | | |

Table 2: Terminal assignment and contact description



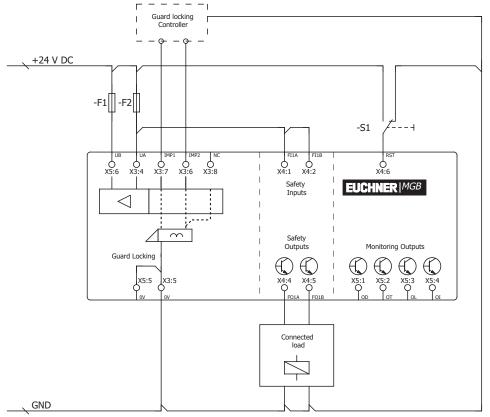
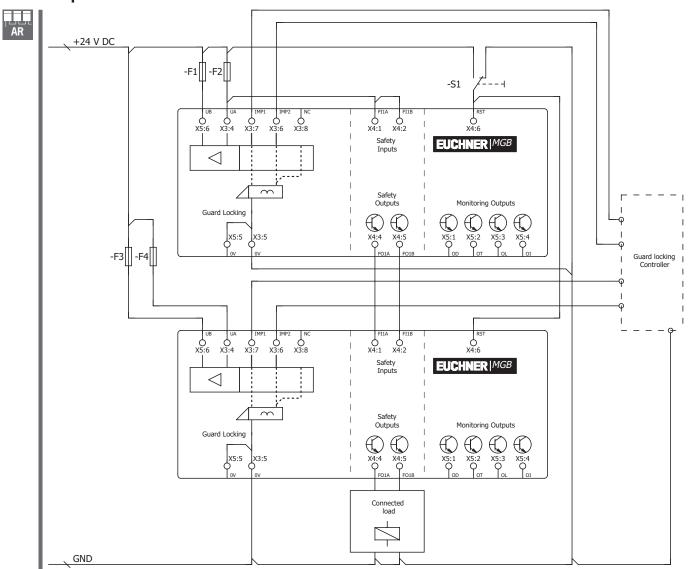


Figure 18: Connection example for separate operation

The switches can be reset via the RST input. To do this, a voltage of 24 V is applied to the RST input for at least 3 seconds. The supply voltage to the switches is interrupted during this time. The RST input must be connected to 0 V if it is not used.



12.11. Operation in an AR switch chain

Figure 19: Connection examples for operation in a CES-AR switch chain

For detailed information on operation in an AR switch chain, see the related CES-AR operating instructions. The locking module MGB-L1-AR-.../MGB-L2-AR-... behaves in the switch chain in practice like a safety switch CES-AR. The differences to the CES-AR are described in the following.

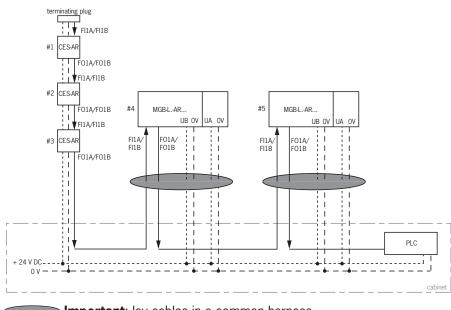
12.12. Information on operation in an AR switch chain

AR 12.12.1. System times

The locking module has longer reaction times than a CES-AR switch (see chapters 14. Technical data on page 36 and 14.2. Typical system times on page 38).

12.12.2. Wiring an AR switch chain

To prevent earth loops, the wiring should be in a star configuration (see Figure 20).



Important: lay cables in a common harness

Figure 20: Central wiring of an AR switch chain in the control cabinet

12.12.3. Number of devices in switch chains

In a pure MGB switch chain a maximum of ten devices can be connected in series. In mixed switch chains (e.g. MGB together with CES-AR) the maximum number of devices is also ten.

12.12.4. Resetting in switch chains



Important!

Use the reset input (RST) for resetting in AR switch chains. All devices in the chain must be reset simultaneously. Resetting individual switches will result in faults.

13. Setup

13.1. Teach-in operation (only for MGB unicode)

The handle module must be assigned to the locking module using a teach-in function before the system comprising locking module and handle module forms a functional unit.

During a teach-in operation the safety outputs are switched off.

| | Important! |
|----------------|---|
| | The locking module disables the code for the previous handle module if teach-in is carried out for a new handle module. Teach-in is not possible again immediately for this device if a new teach-in operation is carried out. The disabled code is deleted in the locking module only after a third code has been taught-in. The locking module can be operated only with the last handle module taught in. If, in the teach-in standby state, the locking module detects the handle module taught-in or a disabled handle module, the teach-in standby state is ended immediately and the locking module changes to normal operation. |
| | If the bolt tongue is in the actuating range for less than 60 s, the handle module is not taught in. |
| (\mathbf{i}) | Tip! |
| | A teach-in adapter (order no. 122369) is available for easier teach-in of AR devices already mounted in a row or for device replacement. It is simply inserted between the connecting cable and the AR device. The device immediately enters teach-in operation on reconnection. After teach-in, the adapter is removed again and the MGB is connected normally. |

Teaching-in handle module

- 1. Fit handle module.
- 2. Close safety device. Check for correct alignment and distance using the marking on the locking module and re-adjust if necessary.
- 3. Insert bolt tongue into the locking module.
- 4. Apply operating voltage to the locking module, optionally connect teach-in adapter.
- The green LED (State) flashes quickly (approx. 5 Hz). A self-test is performed during this time (approx. 10 s in case of AR configuration). Teach-in operation starts, green LED (State) flashes slowly (approx. 1 Hz). During the teach-in operation, the locking module checks whether the handle module is a disabled handle module. Provided this is not the case, the teach-in operation is completed after approx. 60 seconds, and the green LED (State) goes out. The new code has now been stored, and the old code is disabled.
- 5. To activate the handle module's code from the teach-in operation in the locking module, the operating voltage must then be switched off at the locking module for min. 3 seconds. As an alternative, 24 V can be applied to the input RST for at least 3 seconds.

Teach-in in a series connection works analogously. Here, the complete series connection must be restarted using the input RST.

13.2. Mechanical function test

It must be possible to insert the bolt tongue easily into the locking module. To check, close guard several times and actuate door handle.

If available, check function of the escape release. With active guard locking it must be possible to operate the escape release from the inside without excessive effort (approx. 40 N).

13.3. Electrical function test



DIP

WARNING

On usage in a switch chain with different AR devices (e.g. CES-AR, CET-AR), also follow the procedure for the functional check in the related operating instructions.

With active guard lock monitoring

- 1. Switch on operating voltage.
- The locking module carries out a self-test. With BR configuration: the green State LED flashes at 5 Hz for 10 s. The green State LED then flashes at regular intervals.
- 2. Close all guards and insert the bolt tongue into the locking module. In case of guard locking by solenoid force: activate guard locking.
- The safety outputs F01A/F01B
 → are ON.
- The machine must not start automatically.
- It must not be possible to open the guard.
- ➡ The green State LED and the yellow Lock LED are illuminated continuously.
- 3. Enable operation in the control system.
- It must not be possible to deactivate guard locking as long as operation is enabled.
- 4. Disable operation in the control system and deactivate guard locking.
- The guard must remain locked until there is no longer any risk of injury.
- It must not be possible to start the machine as long as guard locking is deactivated.
- ➡ It must be possible to open the guard.

Repeat steps 2-4 for each guard.

With inactive guard lock monitoring

- 1. Switch on operating voltage.
- The locking module carries out a self-test. With BR configuration: the green State LED flashes at 5 Hz for 10 s. The green State LED then flashes at regular intervals.
- 2. Close all guards and insert the bolt tongue into the locking module. As soon as the bolt tongue is inserted into the locking module, the safety outputs FO1A/FO1B are ON. Independent of whether the guard locking is active or not.
- ➡ The machine must not start automatically.
- The green State LED illuminates continuously. The yellow Lock LED is ON for a long time with a short interruption or is ON continuously (depending on the state of the guard locking).
- 3. Enable operation in the control system.
- 4. If necessary, deactivate guard locking and open guard.
- ➡ The machine must switch off and it must not be possible to start it as long as the guard is open.

Repeat steps 2-4 for each guard.

14. Technical data

 (\mathbf{i})

NOTICE

If a product data sheet is included with the product, the information on the data sheet applies in case of discrepancies with the operating instructions.

| Parameter | Value | | Unit |
|--|---|--|-----------------|
| Housing material | | Fiber glass reinforced plastic | |
| | Die-cast zinc, nic | | |
| | Stainless s | | |
| Dimensions | See chapter 7.4. Dimension | n drawing on page 13 | |
| Veight | | | |
| Locking module | 0.75 | | ka |
| Handle module | 1.00 | | kg |
| Escape release | 0.50 | | |
| Ambient temperature at $U_B = DC 24 V$ | -20 + | 55 | °C |
| Degree of protection | | | |
| Cover not populated/populated with buttons/indi- | | | |
| cators/selector switches | IP65 | | |
| | IP54 | | |
| Cover populated with key-operated switch | IF 34 | | |
| Cover populated with key-operated rotary switch | | | |
| S22 | IP 42 | | |
| Safety class | | | |
| Degree of contamination | 3 | | |
| nstallation orientation | Any | | |
| ocking force F _{7h} acc. to EN ISO 14119 | 2,000 | | N |
| Connection | 4 cable entries M20x1.5 | or plug connector | |
| Conductor cross-section (rigid/flexible) | 0.13 1.5 (AWG 2 | | |
| With ferrule acc. to DIN 46228/1 | 0.25 1 | | mm ² |
| With ferrule with collar acc. to DIN 46228/1 | 0.25 0 | | |
| | 0.25 0 | .15 | |
| Operating voltage UB (reverse polarity protected, | 24 +10% / -15 | % (PELV) | V DC |
| egulated, residual ripple < 5%) | | | |
| Auxiliary voltage UA (reverse polarity protected, | 24 +10% / -15 | % (PELV) | V DC |
| egulated, residual ripple < 5%) | | | |
| Current consumption I _{UB} (no load on any outputs) | 80 | | mA |
| Current consumption I _{UA} | | | |
| With energized guard locking solenoid and | 375 | | |
| unloaded outputs OI, OL, OT and OD | | | mA |
| Pushbutton S (unloaded, per LED) | 5 | | |
| External fuse | See chapter 12.3. Fuse protection | for power supply on page 24 | |
| Safety outputs F01A/F01B | Semiconductor outputs, p-swit | | |
| Test pulses | AR < 1000 / AP < 300 | | μs |
| Fest-pulse interval | Min. 10 | | ms |
| Dutput voltage U_{F01A} / U_{F01B}^{1} | | 5 | 1113 |
| HGH U_{F01A} / U_{F01B} | U _B -2V | | |
| | 5 | 5 | VDC |
| | 0 1 1 200 | | V DC |
| Switching current per safety output | | | mA |
| Switching current per control input IMP1, IMP2 and IMM | | | mA |
| Jtilization category acc. to EN IEC 60947-5-2 | DC-13 24 V 200 mA | | |
| | Caution: Outputs must be protected by a free-wheeling diode in the case of inductive loads. | | |
| Nonitoring outputs | p-switching, short circuit-proof | | |
| Output voltage 1) | U _A - 2V U _A | | |
| Max. load | Max. 50 | | mA |
| Rated insulation voltage U _i | 30 | | V |
| Rated impulse withstand voltage U _{imp} | 1.5 | | kV |
| Resilience to vibration | Acc. to EN IEC 60947-5-3 | | rv |
| Switching frequency | Acc. to EN IEC 60947-5-3 0.25 | | LI |
| | 0.25 Acc. to EN IEC 60947-5-3 | | Hz |
| MC protection requirements | | | |
| Reliability values acc. to EN ISO 13849-1 | Guard lock monitoring | Control of guard locking | |
| Category | 4 | 4 | |
| Performance Level | PL e | PL e | |
| 2FH _D | 3.7 x 10 ⁻⁹ / h ²⁾ | 2.8 x 10 ⁻⁹ / h ²⁾ | |
| lission time | 20 | 20 | years |
| lechanical life | 1 x 10 | 5 | |
| In case of use as door stop, and 1 Joule impact | 0.1 1/ | 20 | |
| energy | 0.1 x 10 ⁶ | | |
| 10D (emergency stop) | 0.065 x 1 | 06 | |
| mergency stop | 0.000 X | | |
| | 5 24 | | V |
| Inerating voltage | L 0. | | |
| | | | |
| perating current | 1 10 | 0 | |
| perating current Breaking capacity, max. | 1 10 250 | 0 | mW |
| perating current reaking capacity, max. ower supply LED | 1 10 | 0 | |
| perating current reaking capacity, max. ower supply LED controls and indicators | 1 10 250 24 | 0 | V DC |
| perating current reaking capacity, max. ower supply LED controls and indicators operating voltage | 1 10 250 24 UA | | V DC |
| perating current reaking capacity, max. ower supply LED controls and indicators operating voltage | 1 10 250 24 UA 1 10 | | V DC |
| Derating voltage Derating current Veraking capacity, max. Veraking capacity, max. Veraking capacity, max. Veraking voltage Derating voltage Derating current Veraking capacity, max. | 1 10 250 24 UA | | V DC |

1)

Values at a switching current of 50 mA without taking into account the cable length. Applying the limit value from EN ISO 13849-1:2008, section 4.5.2 (MTTFd = max. 100 years), the employers' liability insurance association certifies a PFHd of max. 2.47 x 10⁸. 2)

14.1. Radio frequency approvals (for devices with FCC ID and IC on the type label)

Product description: Safety Switch

FCC ID: 2AJ58-09

IC: 22052-09

FCC/IC-Requirements

This device complies with part 15 of the FCC Rules and with Industry Canada's licence-exempt RSSs. Operation is subject to the following two conditions:

1) This device may not cause harmful interference, and

2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes :

(1) l'appareil ne doit pas produire de brouillage, et

(2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

This device complies with the Nerve Stimulation Exposure Limits (ISED SPR-002) for direct touch operations.

Cet appareil est conforme aux limites d'exposition relatives à la stimulation des nerfs (ISED CNR-102) pour les opérations tactiles directes.

Supplier's Declaration of Conformity 47 CFR § 2.1077 Compliance Information

Unique Identifier:

MGB-LO-AR Series MGB-L1-AR Series MGB-L2-AR Series MGB-L0-AP Series MGB-L1-AP Series MGB-L2-AP Series

Responsible Party – U.S. Contact Information EUCHNER USA Inc.

6723 Lyons Street East Syracuse, NY 13057

+1 315 701-0315 +1 315 701-0319 info(at)euchner-usa.com http://www.euchner-usa.com

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14.2. Typical system times

i

Important!

The system times given are maximum values for one device.

Ready delay:



In case of AR configuration, the following applies: After switching on, the device carries out a self-test for 10 s. The system is ready for operation only after this time.

In case of AP configuration, the following applies: After switching on, the device carries out a self-test for 0.5 s. The system is ready for operation only after this time.

Turn-on time of safety outputs:



I In case of AR configuration, the following applies: The max. reaction time from the moment when the guard is locked to the moment when the safety outputs switch on T_{on} is 570 ms.

In case of AP configuration, the following applies: The max. reaction time from the moment when the bolt tongue is inserted to the moment when the safety outputs switch on T_{on} is 570 ms.

Simultaneity monitoring of safety inputs FI1A/FI1B: If the safety inputs have different switching states for longer than 150 ms, the safety outputs FO1A/FO1B will be switched off. The device switches to the fault state.

Risk time according to EN 60947-5-3:



<u>000000</u>

With active guard lock monitoring, the following applies: If guard locking is no longer effective, the safety outputs F01A and F01B I are deactivated after a maximum of 350 ms.

This value applies to a single switch. For each additional switch in a chain the risk time increases by 5 ms.

With inactive guard lock monitoring, the following applies: If the bolt tongue is pulled out of the locking module, the safety outputs F01A and F01B are deactivated after a maximum of 350 ms.

This value applies to a single switch. For each additional switch in a chain the risk time increases by 5 ms.

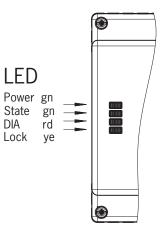
Difference time: The safety outputs FO1A and FO1B switch with a slight time offset. They both have the ON state at the latest after a difference time of 10 ms.

Time offset: The max. permissible time offset between switch-on of operating voltage UB and auxiliary voltage UA is 1 s.

15. System states

15.1. Key to symbols

| 0 | LED not illuminated |
|---|------------------------------------|
| ✷ | LED illuminated |
| | LED flashes for 8 seconds at 10 Hz |
| | LED flashes three times |
| Х | Any state |



15.2. System status table MGB-AR

| $ \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$ | | | Doe | | àua | | 00 | | | | | | | | | | |
|---|---|--------|-------------|--------------|-------------|-----|-----|-----|-----|---------|---------------|---------|-----------------------|-----------|-----------------|-----------------------|---|
| X X X X V OF | Operating mode | | or position | | ard locking | | | | | | Power (green) | (8,000) | STATE (green) | DIA (red) | _ you (you only | Lock (vellow) | State |
| X Quene Iodainsected GF GF <thgf< th=""> <thgf< th=""> <thgf< th=""></thgf<></thgf<></thgf<> | Self-test | × | × | × | × | OFF | OFF | OFF | OFF | OFF | | * | 5 Hz | | 0 | | Self-test after power-up |
| X doed Interface OFF O | | × | open | not insertec | | OFF | OFF | OFF | OFF | OFF | | | long OFF, short ON | | 0 | | Normal operation, door open |
| OFF doted inserted OFF OFF <th< td=""><td></td><td>×</td><td>closed</td><td></td><td></td><td>OFF</td><td>NO</td><td>OFF</td><td>OFF</td><td>OFF</td><td></td><td></td><td>long ON, short OFF</td><td></td><td>0</td><td></td><td>Normal operation, door closed</td></th<> | | × | closed | | | OFF | NO | OFF | OFF | OFF | | | long ON, short OFF | | 0 | | Normal operation, door closed |
| Old closed liserted OFF ON OFF ON OFF OFF ON OFF | | OFF | closed | | OFF | OFF | NO | NO | OFF | OFF | | | long ON, short OFF | | | long ON, short OFF | Normal operation, door closed, bolt tongue inserted, safety inputs FI1A/FI1B OFF |
| ON Cosed Inserted ON OF ON ON OF | Normal oper- ation | 20 | | | E C | OFF | 2 | Z | J. | Cer Cer | | | long ON, short OFF | | | long ON, | With active guard lock monitoring: normal operation, door closed, bolt tongue inserted. Safety inputs FI1A/FI1B are ON. Safety outputs F01A and F01B 🕑 are OFF |
| OF losed iserted ON OF ON OF ON OF ON OF ON OF ON OF Sector Sector <td></td> <td>20</td> <td>closed</td> <td></td> <td>5</td> <td>NO</td> <td>5</td> <td></td> <td></td> <td>5</td> <td></td> <td>✻</td> <td></td> <td>0</td> <td></td> <td>short OFF</td> <td>With inactive guard lock monitoring: normal operation, door closed, bolt tongue inserted. Safety inputs FI1A/FI1B are ON. Safety outputs F01A and F01B are ON</td> | | 20 | closed | | 5 | NO | 5 | | | 5 | | ✻ | | 0 | | short OFF | With inactive guard lock monitoring: normal operation, door closed, bolt tongue inserted. Safety inputs FI1A/FI1B are ON. Safety outputs F01A and F01B are ON |
| ON closed inserted ON | | OFF | closed | | NO | OFF | NO | NO | NO | OFF | | | long ON, short OFF | | ✻ | | Operation in an AR chain: normal operation, door closed and locked. Safety outputs on the previous device OFF |
| dby x open not inserted OFF OFF OFF OFF OFF OFF \longrightarrow 3x \bigcirc <th< td=""><td></td><td>NO</td><td>closed</td><td></td><td>NO</td><td>NO</td><td>NO</td><td>NO</td><td>NO</td><td>OFF</td><td></td><td>і</td><td></td><td></td><td>✻</td><td></td><td>Operation as separate device: normal operation, door closed and locked Operation in an AR chain: normal operation, door closed and locked. Safety outputs on the previous device ON</td></th<> | | NO | closed | | NO | NO | NO | NO | NO | OFF | | і | | | ✻ | | Operation as separate device: normal operation, door closed and locked Operation in an AR chain: normal operation, door closed and locked. Safety outputs on the previous device ON |
| XclosedinsertedONOFFOFOFFOOOOOOOOOOOOOO <f< th="">O<f< th=""><th< td=""><td>Teach-in standby (only for MGB unicode)</td><td></td><td>open</td><td>not insertec</td><td></td><td>OFF</td><td>OFF</td><td>OFF</td><td>OFF</td><td>OFF</td><td>✻</td><td>☀</td><td>ж Ю</td><td></td><td>0</td><td></td><td>Door open; device is ready for teach-in of another handle module (only 3 min. after Power UP)</td></th<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<></f<> | Teach-in standby (only for MGB unicode) | | open | not insertec | | OFF | OFF | OFF | OFF | OFF | ✻ | ☀ | ж Ю | | 0 | | Door open; device is ready for teach-in of another handle module (only 3 min. after Power UP) |
| $ \begin{array}{ c c c c c c c c c c c c c c c c c c c$ | Setup (only for MGB | × | closed | | NO | OFF | OFF | OFF | OFF | OFF | | * | 1 Hz | | 0 | | Tip for teach-in operation: to prevent the interruption of teach-in operations, close door and switch on guard locking. |
| X | unicode) | × | × | × | × | OFF | OFF | OFF | OFF | OFF | | 0 | | | 0 | | Positive acknowledgment after completion of teach-in operation |
| errone x x ont ont x | | × | × | × | × | OFF | OFF | OFF | OFF | NO | | * | 1 X | | 0 | | Error during teach-in/configuration or invalid DIP switch setting |
| X | | errone | | × | × | OFF | OFF | OFF | OFF | NO | | ☀ | 2 x | | 0 | | FI1A/FI1B input error (e.g. missing test pulses, illogical switching state from previous switch) |
| X X X X X X X X X X X X X X X X X X X X X X X X X X X <td></td> <td>×</td> <td>×</td> <td>×</td> <td>×</td> <td>OFF</td> <td>×</td> <td>×</td> <td>×</td> <td>OFF</td> <td></td> <td>*</td> <td>3 x</td> <td>✻</td> <td>0</td> <td></td> <td>Handle module read error (e.g. error in code)</td> | | × | × | × | × | OFF | × | × | × | OFF | | * | 3 x | ✻ | 0 | | Handle module read error (e.g. error in code) |
| x x x off off off off x x x off off off off x x x off off off off x x off off off off off | Diagnostics | × | × | × | × | OFF | OFF | OFF | OFF | NO | | * | 4 x | <u>,</u> | 0 | | Output fault (e.g. short circuit, loss of switching capability) or short circuit at the outputs |
| X X X OFF OFF OFF ON OFF ON OFF ON OFF OFF ON OFF OFF | | × | × | × | × | × | OFF | OFF | OFF | N | | 0 | | | 0 | | Internal fault (e.g. component faulty, data error) |
| X X X OFF OFF ON OF ST | | × | × | × | × | OFF | OFF | OFF | OFF | NO | | 0 | | | * | 1 × | Signal sequence erroneous (e.g. broken bolt tongue). With active release monitoring: escape release or auxiliary release was actuated |
| | | × | × | × | × | × | OFF | OFF | OFF | NO | | 0 | _ | * | * | 2 x | Control inputs IMP1 , IMP2, IMM invalid; switch control inputs off for min. $arkappa$ s and switch on again to reset |

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15.3. System status table MGB-AP

| | | | | | | | -AP | ch on guard locking. | | | | | | | to reset |
|---------------|--------------------------------|-----------------------------|-------------------------------|---|---|---|---|---|--|---|---|---|--|--|---|
| | State | Normal operation, door open | Normal operation, door closed | With active guard lock monitoring: normal operation, door closed, bolt tongue inserted. Safety outputs FOIA and FOIB $\underline{\mathbb{W}}$ are OFF | With inactive guard lock monitoring: normal operation, door closed, bolt tongue inserted. Safety outputs FOIA and FOIB are ON | Normal operation, door closed and locked. | Door open; device is ready for teach-in of another handle module (only 3 min. after Power UP) | Tip for teach-in operation: to prevent the interruption of teach-in operations, close door and switch on guard locking. | Positive acknowledgment after completion of teach-in operation | Error during teach-in/configuration or invalid DIP switch setting | Handle module read error (e.g. error in code) | Output fault (e.g. short circuit, loss of switching capability) or short circuit at the outputs | internal fault (e.g. component faulty, data error) | Signal sequence erroneous (e.g. broken bolt tongue). With active release monitoring: escape release or auxiliary release was actuated | Control inputs IMP1, IMP2, IMM invalid; switch control inputs off for min. ½ s and switch on again to reset |
| | Sta | N | N | | short OFF Wil | No | Do | Tip | Po: | Err | Har | Out | Inte | 1 × Sig | 2 x Co |
| | Lock (yellow) | 0 | 0 | | sho | ✻ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | * | * |
| ator | DIA (red) | | | | , t C | | | | | | | * | | · · · | * |
| LED indicator | | long OFF, short ON | long ON, short OFF | long ON, short OFF | | | 3 x | 1 Hz | | 1 × | 3 x | 4 × 1 | | | |
| | State (green) | | - s | - 00 | і | і | * | * | 0 | * | * | * | 0 | 0 | 0 |
| - | Power (green) | | | 1 | 1 | | Þ | K | | | | 1 | 1 | | |
| | nostics monitoring out (OI) | OFF | OFF | Ę | 40 | OFF | OFF | OFF | OFF | NO | OFF | NO | NO | NO | NO |
| | rd lock monitoring out (OL) | OFF | OFF | Ŀ | 10 | NO | OFF | OFF | OFF | OFF | × | OFF | OFF | OFF | OFF |
| | tongue monitoring out (OT) | OFF | OFF | ā | Z | NO | OFF | OFF | OFF | OFF | × | OFF | OFF | OFF | OFF |
| Doo (OD) | r monitoring output | OFF | NO | ā | Z | NO | OFF | OFF | OFF | OFF | × | OFF | OFF | OFF | OFF |
| | ety outputs FO1A FO1B | OFF | OFF | OFF | NO | NO | OFF | OFF | OFF | OFF | OFF | OFF | × | OFF | × |
| Gua | rd locking | OFF | OFF | L | 5 | NO | OFF | NO | × | × | × | × | × | × | × |
| Posi tong | tion of the bolt gue | not inserted | not inserted | - | Inserted | inserted | not inserted | inserted | × | × | × | × | × | × | × |
| Doo | r position | open n | closed n | | closed | closed | open n | closed | × | × | × | × | × | × | × |
| | Operating mode | | · | Normal oper- ation | | | Teach-in standby (only for MGB unicode) | Setup (only for MGB | unicode) | | | Diagnostics | | | |

16. Troubleshooting and assistance

16.1. Resetting errors

Proceed as follows:

- 1. Open the guard.
- 2. Switch off operating voltage at the locking module for min. 3 seconds or connect 24 V to the input RST for min. 3 seconds.

Alternatively, the internal reset (see 7. System overview on page 12) can be pressed for 3 seconds with a pointed object, e.g. ball-point pen.

- The green LED (State) flashes quickly (approx. 5 Hz in case of AR configuration). A self-test is performed during this time (approx. 10 s in case of AR configuration). The LED then cyclically flashes three times.
- 3. Close guard and switch on guard locking.
- ➡ The system is in normal operation again.

16.2. Troubleshooting help on the Internet

You will find a help file on troubleshooting under Downloads in the service area at www.euchner.com.

16.3. Mounting help on the Internet

You will find an animation on the mounting process at www.euchner.com.

16.4. Application examples

You will find application examples on connecting the device to various control systems at www.euchner.com.

17. Service

If servicing is required, please contact: EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Germany

Service telephone: +49 711 7597-500

E-mail: info@euchner.de

Internet: www.euchner.com

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18. Inspection and service

WARNING

Loss of the safety function because of damage to the device. In case of damage, the affected module must be replaced completely. Only accessories or spare parts that can be ordered from EUCHNER may be replaced.

 Check the device for proper function at regular intervals and after every fault. For information about possible time intervals, refer to EN ISO 14119:2013, section 8.2.

Regular inspection of the following is necessary to ensure trouble-free long-term operation:

- · Check the switching function (see chapter 13.3. Electrical function test on page 35)
- · Check the secure mounting of the devices and the connections
- Check for soiling

No servicing is required. Repairs to the device are only allowed to be made by the manufacturer.

| NOTICE |
|--|
| The year of manufacture can be seen in the lower right corner of the rating plate. |
| |

19. Declaration of conformity

| | | EU-Konformitätserklä EU declaration of co Déclaration UE de co Dichiarazione di coni Declaración UE de co | nformity nformité formità UE | | Original DE Translation EN Traduction FR Traduzione IT Traducción ES |
|---|---|--|--|---|--|
| The beneau Les produit I prodotti so | gend aufgeführten Produkte sind kor h listed products are in conformity w s mentionnés ci-dessous sont confor tto elencati sono conformi alle diretti tos listados a continuación son confo | ith the requirements of the follo rmes aux exigences imposées p ive sotto riportate (dove applica | wing directives (i par les directives bili): | f applicable): suivantes (si valable |) |
| 1: | Maschinenrichtlinie Machinery directive Directive Machines Direttiva Macchine Directiva de màquinas | 2006/42/EG 2006/42/EC 2006/42/CE 2006/42/CE 2006/42/CE | | | 4. 4. - 4.1 |
| II | E Funkanlagen-Richtlinie (RTTE Radio equipment directive Directive équipement radioéle Direttiva apparecchiatura radi Directiva equipo radioeléctrico | 1999/5/EC until 2 actrique 1999/5/CE o 1999/5/CE | 2017-06-12 2 2 2 | 014/53/EU ab 2017-(014/53/EU from 201 014/53/UE 014/53/UE 014/53/UE 014/53/UE | |
| | : RoHS Richtlinie RoHS directive Directive de RoHS Direttiva RoHS Directiva RoHS | 2011/65/EU 2011/65/EU 2011/65/UE 2011/65/UE 2011/65/UE | | | |
| Directive éd Gli obiettivi 3.1 della Di Los objetivi equipo radi | s de sécurité de la Directive basse te juipement radioélectrique. di sicurezza della Direttiva bassa ter rettiva apparecchiatura radio. ss de seguridad de la Directiva de ba peléctrico. ormen sind angewandt: | ension 2014/35/UE et Directive nsione 2014/35/UE e Direttiva (ajo voltaje 2014/35/UE y Directi | de CEM 2014/30 CEM 2014/30/UE | /EU sont conformes sono conformi a qua | anto riportato nell´articolo |
| Directive éd Gli obiettivi 3.1 della Di Los objetivi equipo radi Folgende N Following s Les normes Vengono aj | uipement radioélectrique. di sicurezza della Direttiva bassa ter rettiva apparecchiatura radio. os de seguridad de la Directiva de ba peléctrico. | ension 2014/35/UE et Directive nsione 2014/35/UE e Direttiva C ajo voltaje 2014/35/UE y Directiv a: EN 609 b: EN 1SC c: EN 1SC d: EN 609 e: EN 500 f: EN 300 | de CEM 2014/30 CEM 2014/30/UE va CEM 2014/30 | VEU sont conformes sono conformi a que /UE cumplen con el a 2005/A11:2013 | à l'article 3.1 de la anto riportato nell´articolo |
| Directive éd Gli obiettivi 3.1 della Di Los objetivi equipo radi Folgende N Following s Les normes Vengono a Se utilizan Bezeichnun Description Description | uipement radioélectrique. di sicurezza della Direttiva bassa ter rettiva apparecchiatura radio. os de seguridad de la Directiva de ba beléctrico. ormen sind angewandt: tandards are used: s suivantes sont appliquées: oplicate le seguenti norme: os siguientes estándares: Ig der Bauteile of components des composants dei componenti | ension 2014/35/UE et Directive nsione 2014/35/UE e Direttiva C ajo voltaje 2014/35/UE y Directiv a: EN 600 b: EN ISC c: EN ISC c: EN SO c: EN 500 f: EN 300 g: EN 500 Type Type Type Tipo | de CEM 2014/30/UE CEM 2014/30/UE va CEM 2014/30/ 947-5-3:2013 0 14119:2013 0 13849-1:2015 947-55:1997/A1 364:2010 0 330-2 V1.6.1 | VEU sont conformes sono conformi a que /UE cumplen con el a 2005/A11:2013 | à l'article 3.1 de la anto riportato nell´articolo |
| Directive éd Gli obiettivi 3.1 della Di Los objetivi equipo radi Folgende N Following s Les normes Vengono a Se utilizan Bezeichnur Description Description Description Descripción Sicherheitss Safety Swite Interruptore | uipement radioélectrique. di sicurezza della Direttiva bassa ter rettiva apparecchiatura radio. ss de seguridad de la Directiva de ba beléctrico. ormen sind angewandt: fandards are used: suivantes sont appliquées: oplicate le seguenti norme: os siguientes estándares: g der Bautelle of components des composants de components de componentes chalter thes s de sécurité sicurezza s de seguridad | ension 2014/35/UE et Directive nsione 2014/35/UE e Direttiva C ajo voltaje 2014/35/UE y Directiv a: EN 609 b: EN ISC c: EN ISC c: EN 503 f: EN 300 g: EN 503 Type Type Type | de CEM 2014/30/UE Ve CEM 2014/30/UE va CEM 2014/30/ 047-5-3:2013 0 14119:2013 0 13849-1:2015 0 13849-1:2015 0 330-2 V1.6.1 581:2012 (RoHS Richtlinie Directives Directives Directiva Directiva | D/EU sont conformes sono conformi a qua /UE cumplen con el a :2005/A11:2013 s) Normen Standards Normes Normes Norme | à l'article 3.1 de la anto riportato nell'articolo articulo 3.1 de la Directiva Zertifikats-Nr. No. of certificate Numéro du certificat Numero del certificato |
| Directive éd Gli obiettivi 3.1 della Di Los objetivi equipo radi Folgende N Folgende N Following s Les normes Vengono a Se utilizan Bezeichnut Description Description Description Description Description Sicherheitss Safety Switt Interruptore Sicherheitss Safety Switt Interrupteur Finecorsa d | uipement radioélectrique. di sicurezza della Direttiva bassa ter rettiva apparecchiatura radio. ss de seguridad de la Directiva de ba beléctrico. ormen sind angewandt: tandards are used: suivantes sont appliquées: oplicate le seguenti norme: os siguientes estándares: og der Bauteile of components des composants dei componentes chalter thes s de sécurité sicurezza | ension 2014/35/UE et Directive nsione 2014/35/UE e Directiva C ajo voltaje 2014/35/UE y Directiv a: EN 609 b: EN ISC c: EN ISC d: EN 503 f: EN 503 Type Type Type Type Type Typo Typo MGB-LAR MGB-LAR MGB-LAR d'urgence di emergenza MGB-LAP | de CEM 2014/30 CEM 2014/30/UE va CEM 2014/30/UE 947-5-3:2013 0 14119:2013 0 13849-1:2015 947-5-5:1997/A1 364:2010 0 330-2 V1.6.1 581:2012 (RoHS Richtlinie Directive Directive Directiva Directivas | D/EU sont conformes sono conformi a qua /UE cumplen con el a 22005/A11:2013 2005/A11:2013 3) Normen Standards Norme Estándares | à l'article 3.1 de la anto riportato nell'articolo articulo 3.1 de la Directiva Zertifikats-Nr. No. of certificate Numéro du certificato Numero del certificato Número del certificado |

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Die alleinige Verantwortung für die Ausstellung dieser Konformitätserklärung trägt der Hersteller: This declaration of conformity is issued under the sole responsibility of the manufacturer: La présente déclaration de conformité est établie sous la seule responsabilité du fabricant: La presente dichiarazione di conformité è rilasciata sotto la responsabilité esclusiva del fabbricante: La presente declaración de conformita è rilasciata sotto la responsabilitá esclusiva del fabbricante: La presente declaración de conformidad se expide bajo la exclusiva responsabilidad del fabricante:

EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Germany

EUCHNER

More than safety.

EUCHNER

i.A. Dipl.-Ing. (FH) Duc Binh Nguyen Dokumentationsbevollmächtigter Documentation manager Responsable documentation Responsabilità della documentazione Agente documenta

Leinfelden, Januar 2017

EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Germany

i.A. Dipl.-Ing. Richard Holz

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30.01.2017 - NG -KM - Blatt/Sheet/ Page/Pagina/ Página 2 EUCHNER GmbH + Co. KG Kohlhammerstraße 16 70771 Leinfelden-Echterdingen Tel. +49/711/7597-0 Fax +49/711/753316 www.euchner.de info@euchner.de

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